

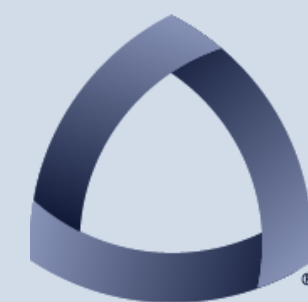
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Estimating Theoretical Error Distributions for Overflight Methane Measurements

Colorado School of Mines

Department of Applied Mathematics and Statistics

Daniel Callan Richards-Dinger
28 September 2023

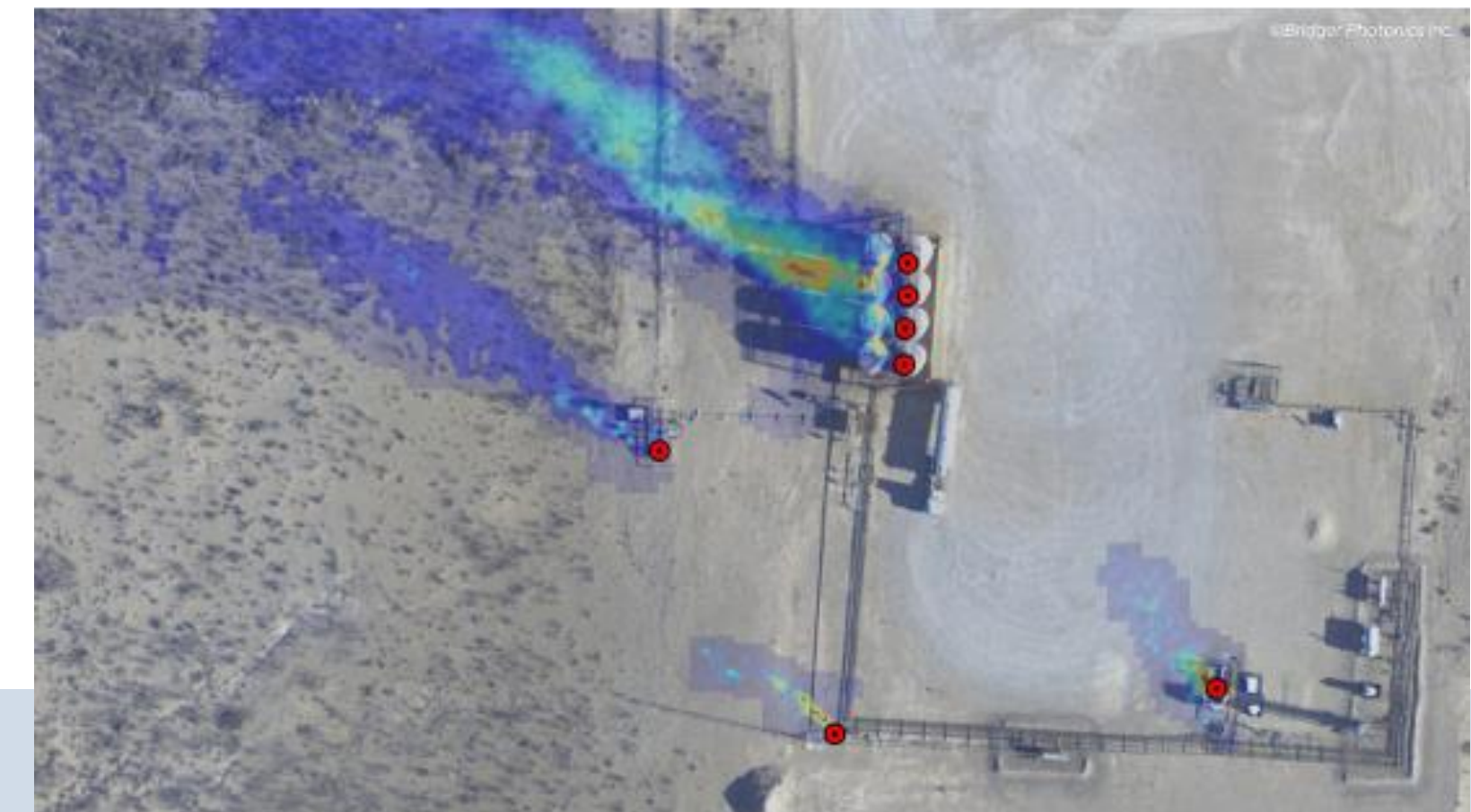


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Motivation



- Increased emphasis on measurement-informed inventories
- New technologies rapidly developing, e.g. Bridger Photonics
- Measurements far more useful with uncertainties
 - ▶ Need robust methods for estimating uncertainty

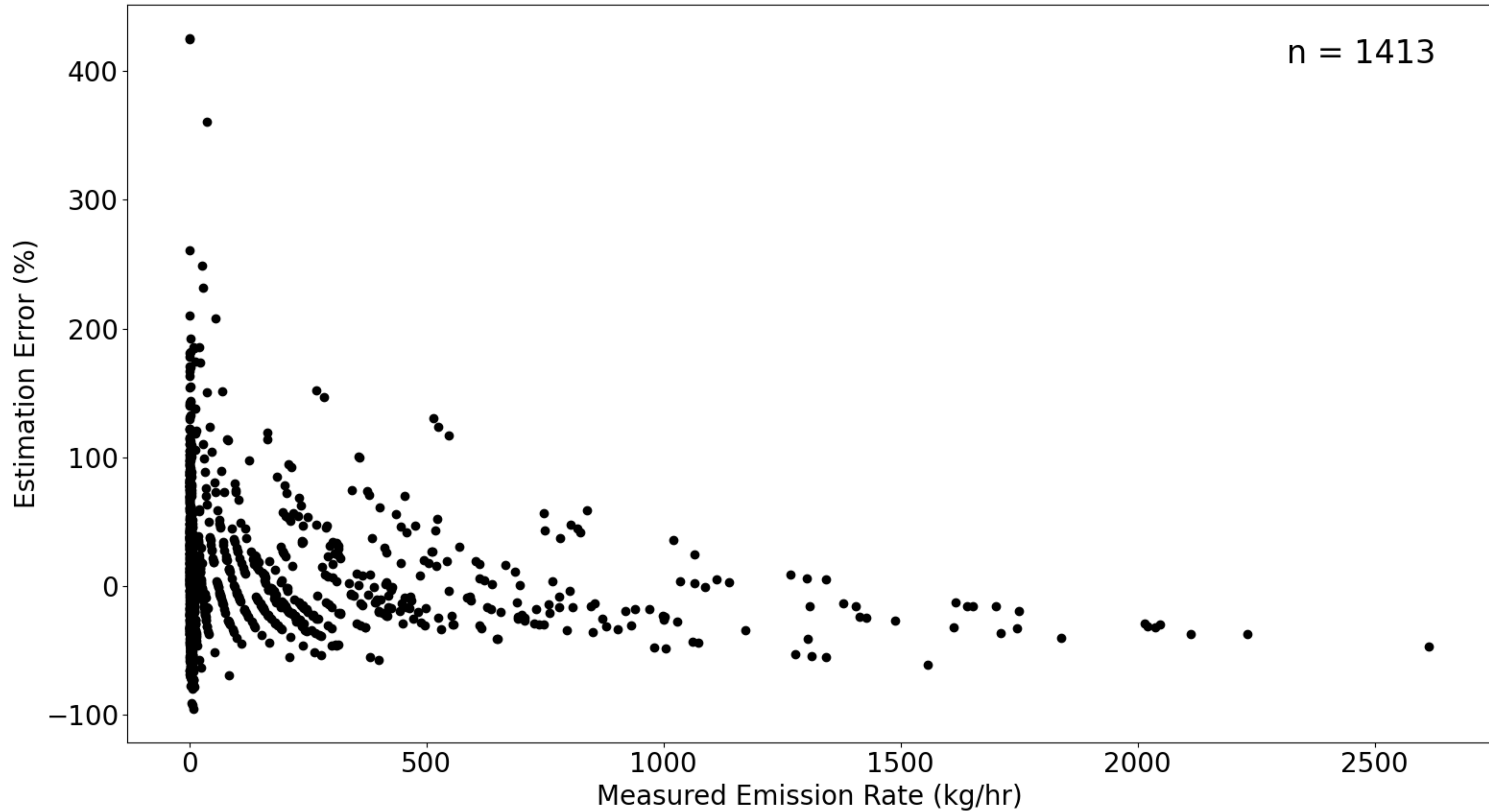


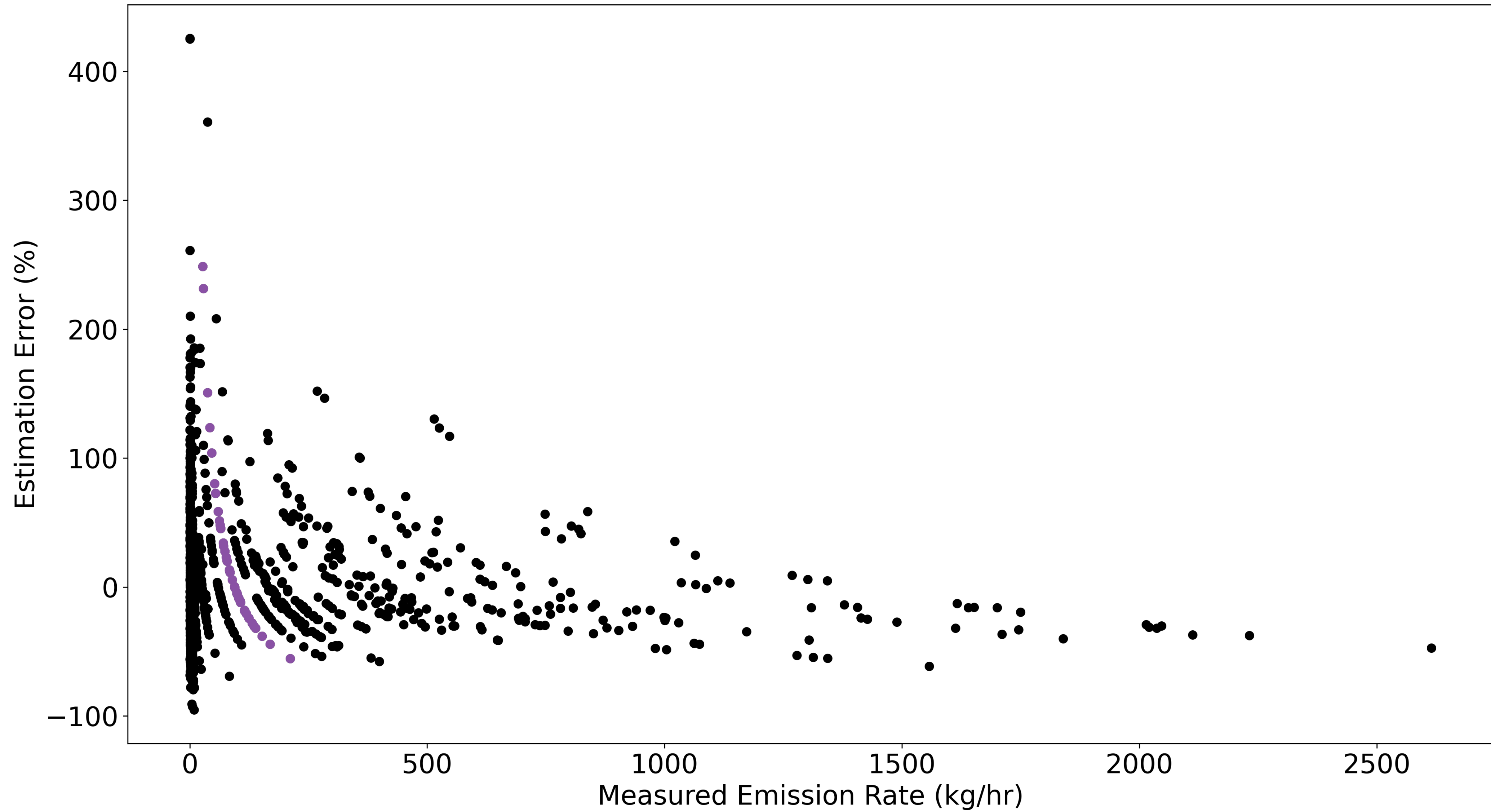
Background

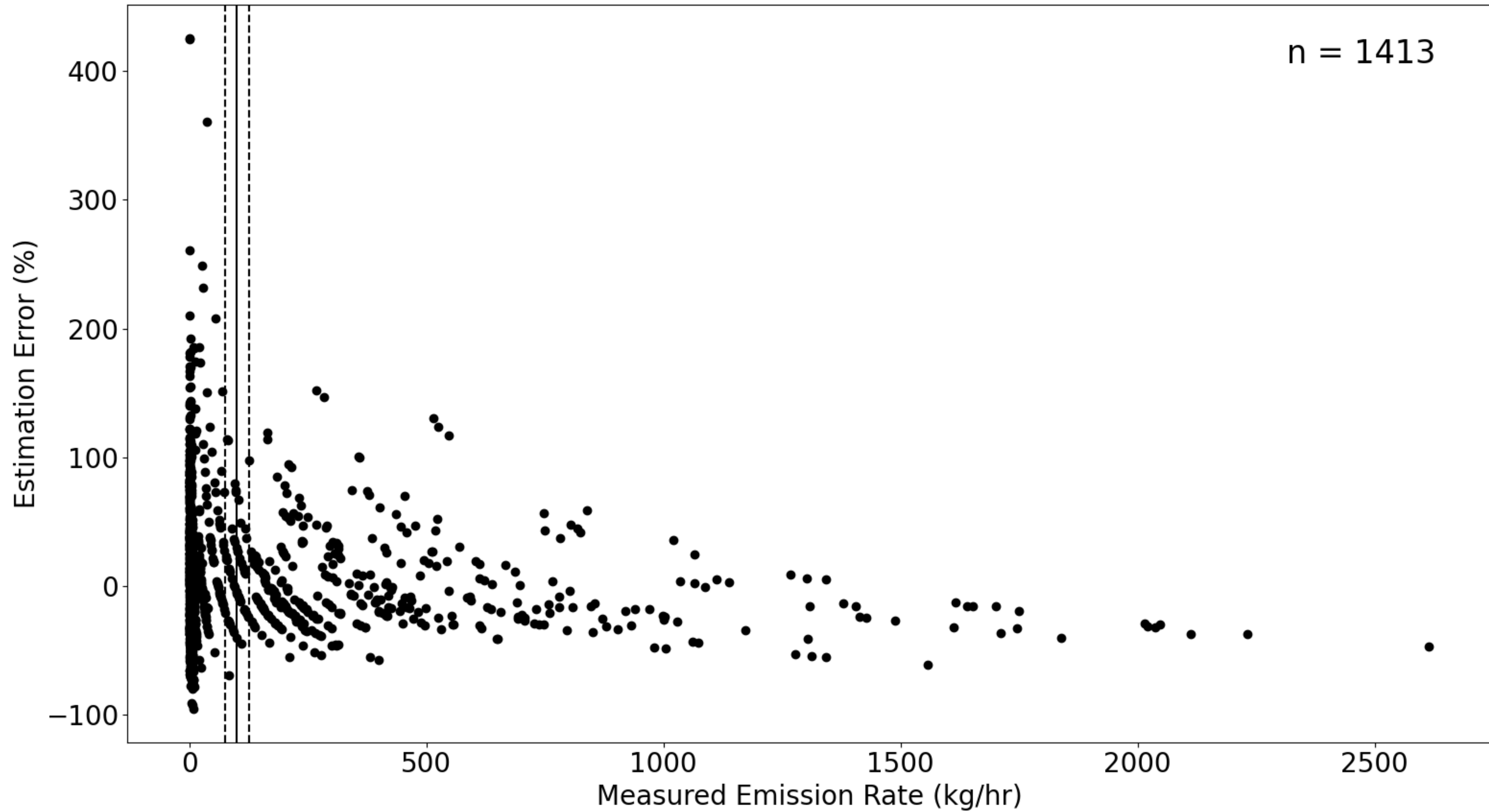
$$\pi(Q|\tilde{Q}) = \int_{\hat{Q}} \pi_{\lambda Q} \left(\frac{Q}{\hat{Q}} \right) \pi_{\kappa Q} \left(\frac{\hat{Q}}{f_B(\tilde{Q})} \right) \frac{1}{\hat{Q} f_B(\tilde{Q})} d\hat{Q}$$

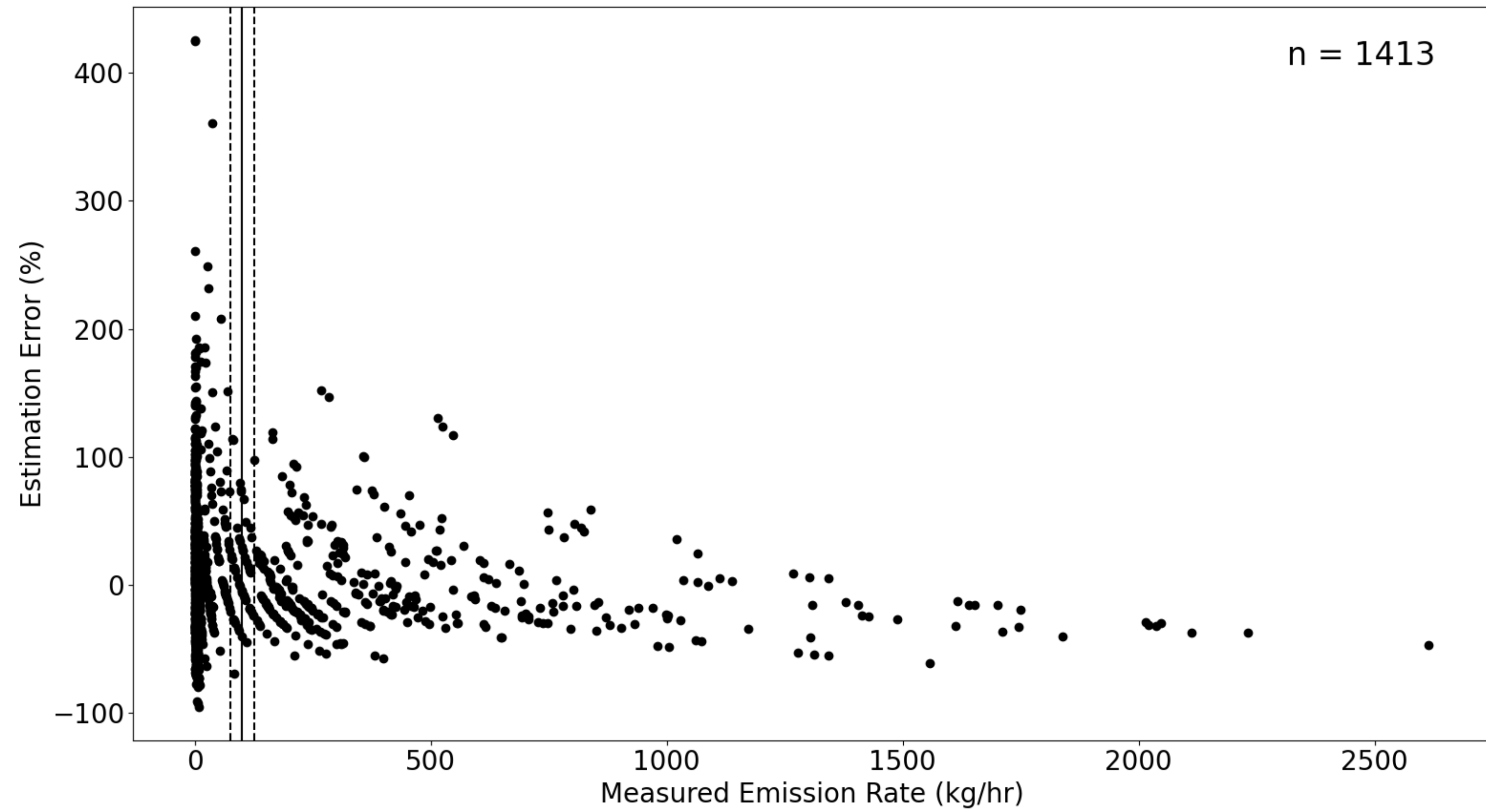
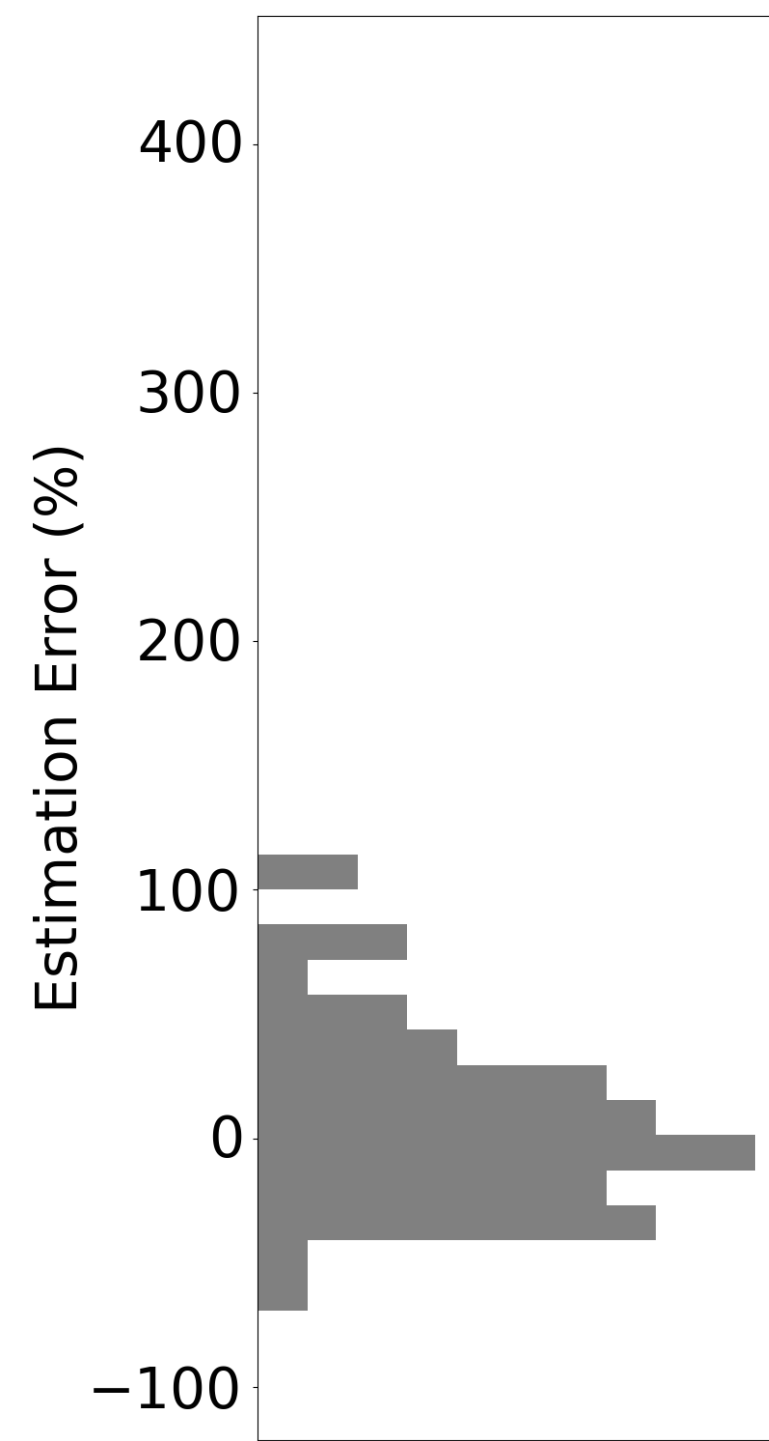
- Conrad, et al. investigated this in their 2023 paper
- Most specific model to date, relative error rate not dependent on measured emission rate
- Our goal: create a flexible framework that can use the best/most available data to estimate error distributions

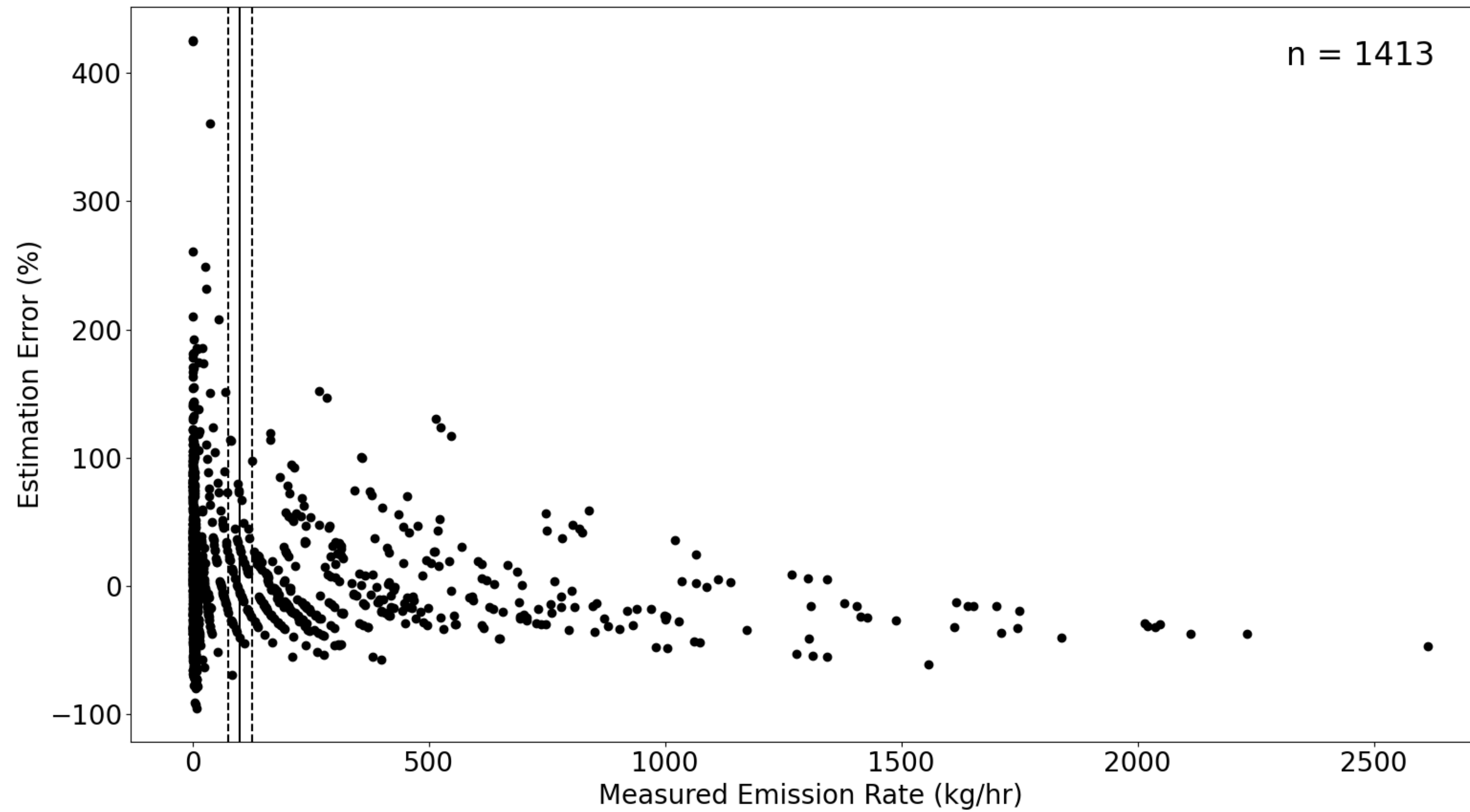
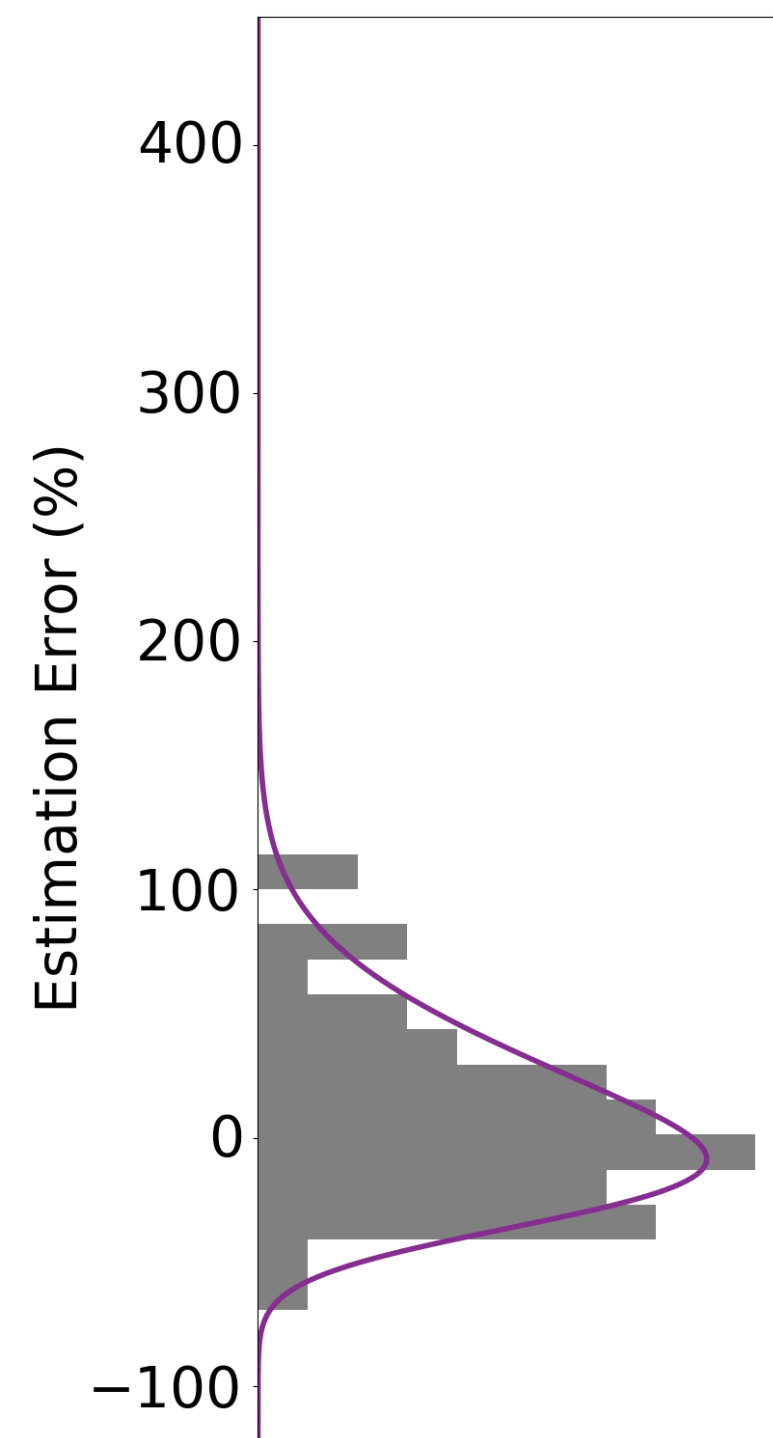
Source: Bradley M. Conrad, David R. Tyner, Matthew R. Johnson,
Robust probabilities of detection and quantification uncertainty for aerial methane detection:
Examples for three airborne technologies,
Remote Sensing of Environment, Volume 288, 2023.





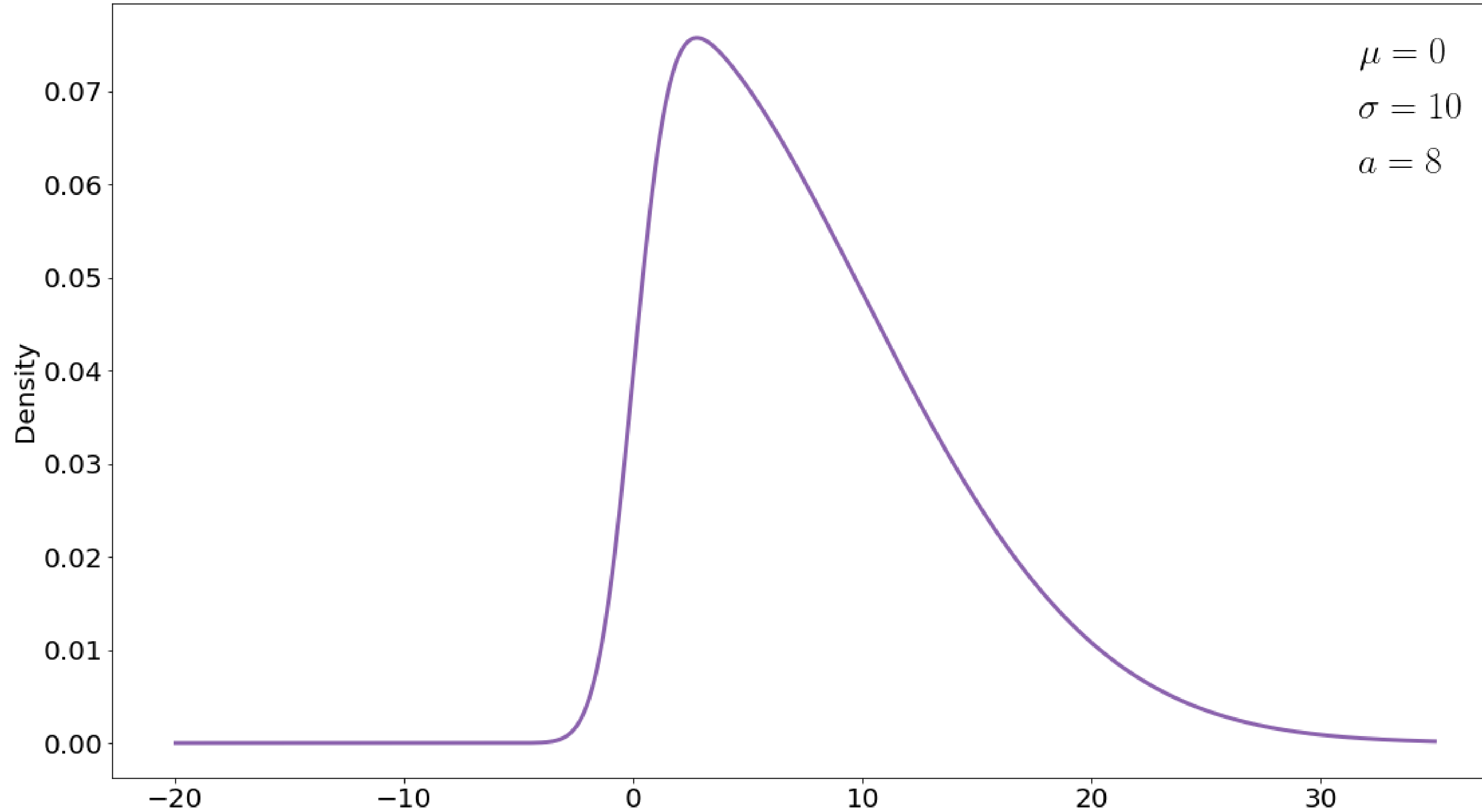






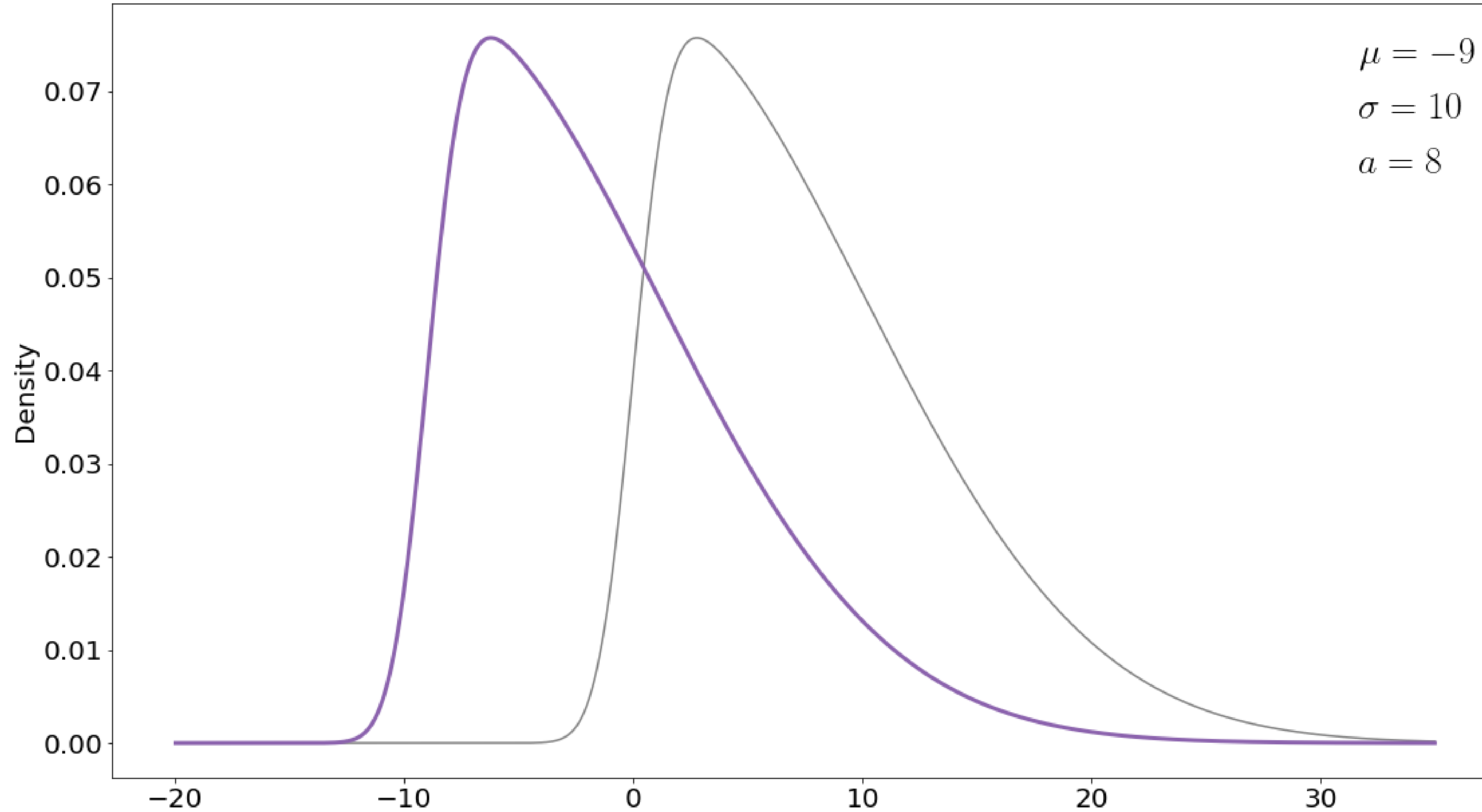
Location Parameter

$$f(x) = \frac{\varphi\left(\frac{x-\mu}{\sigma}\right)\Phi\left(a\frac{x-\mu}{\sigma}\right)}{\sigma\Phi(0)}$$



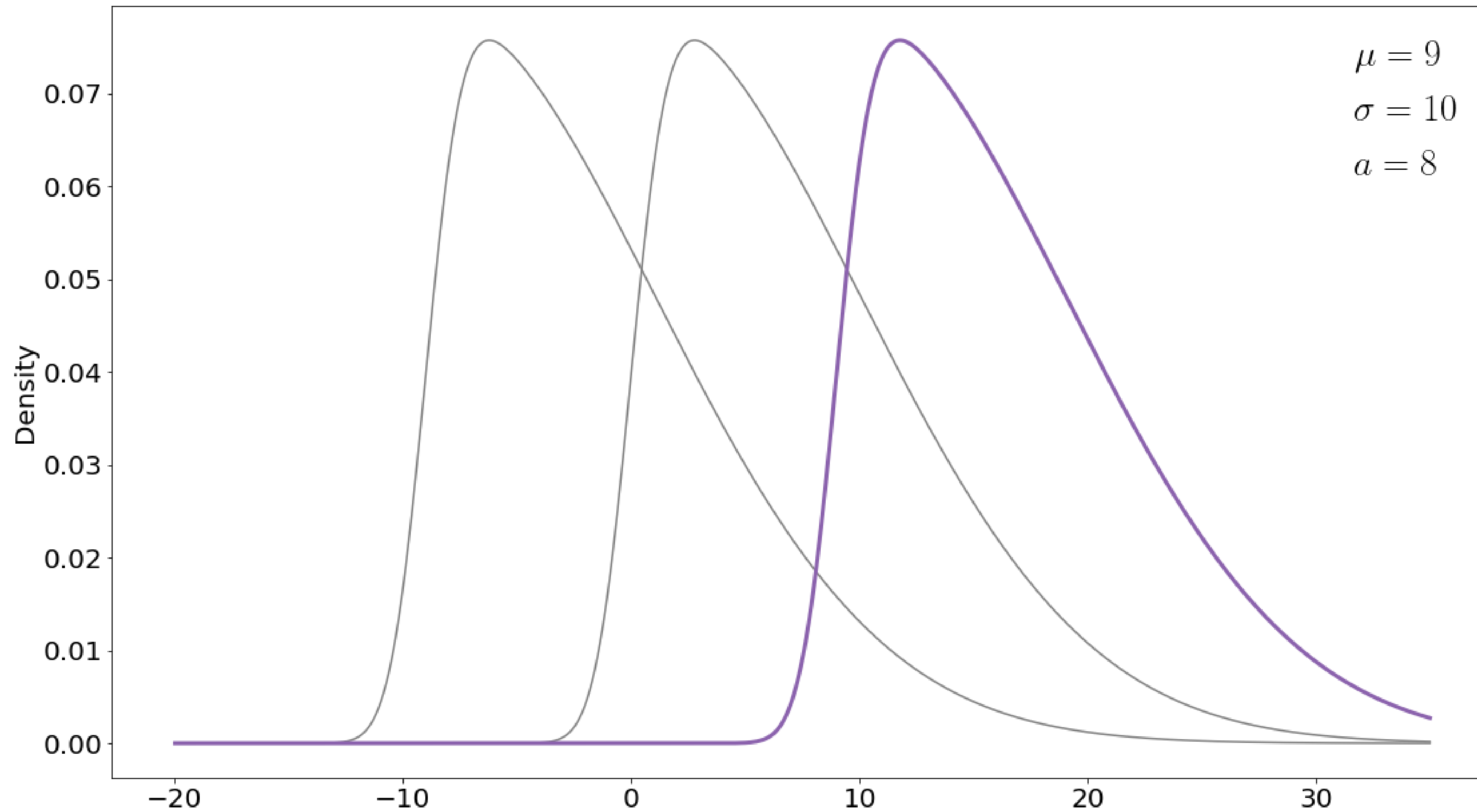
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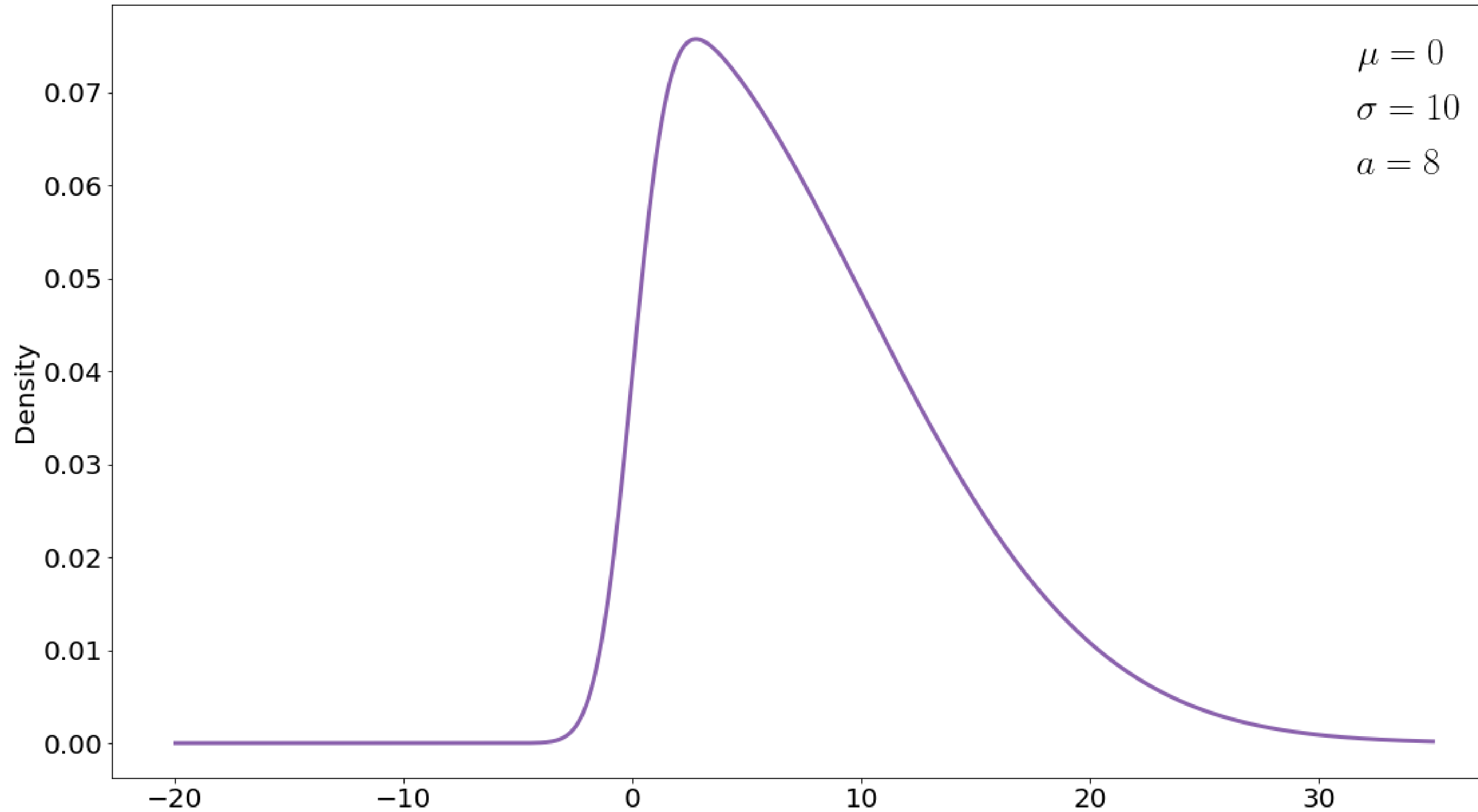
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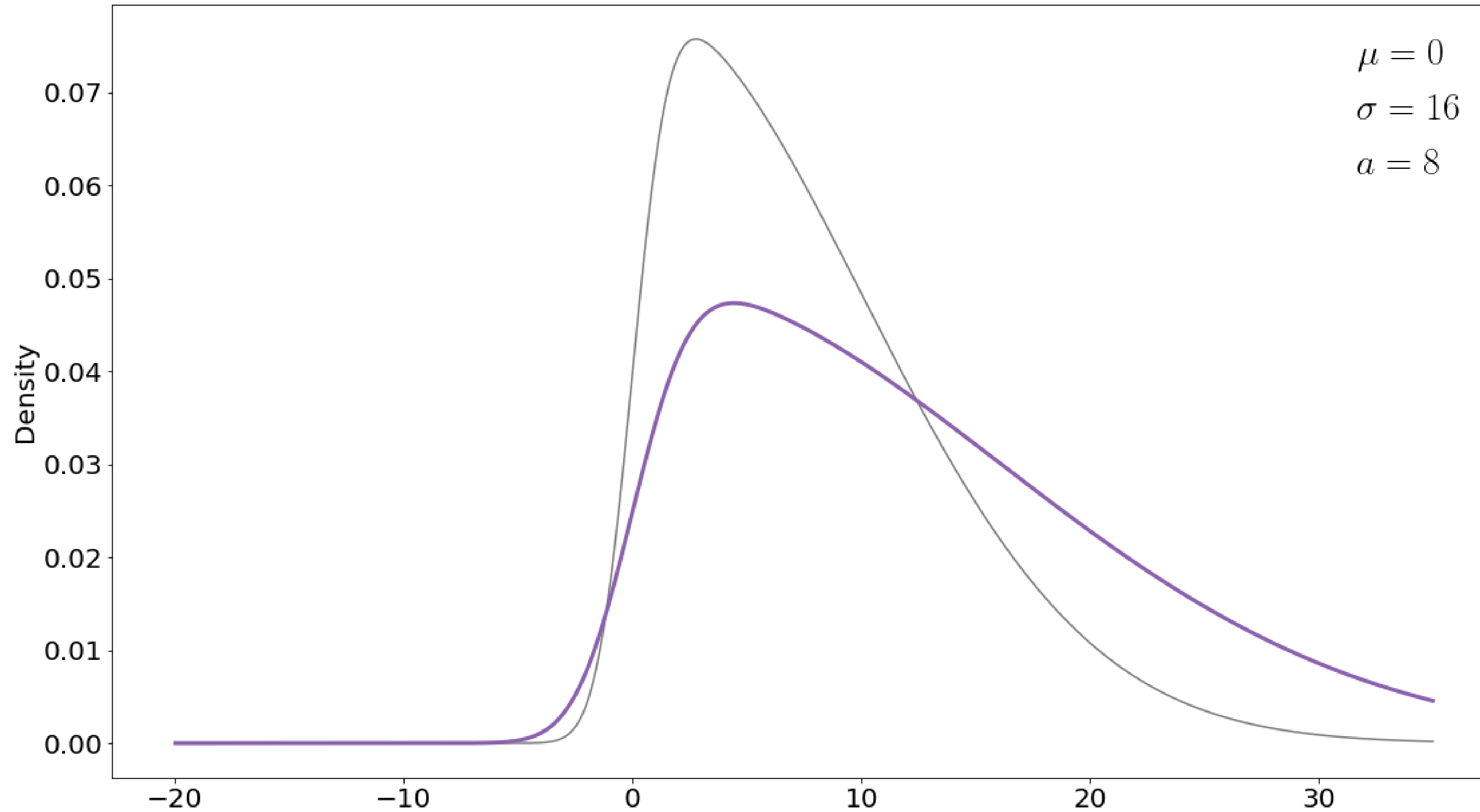
Scale Parameter

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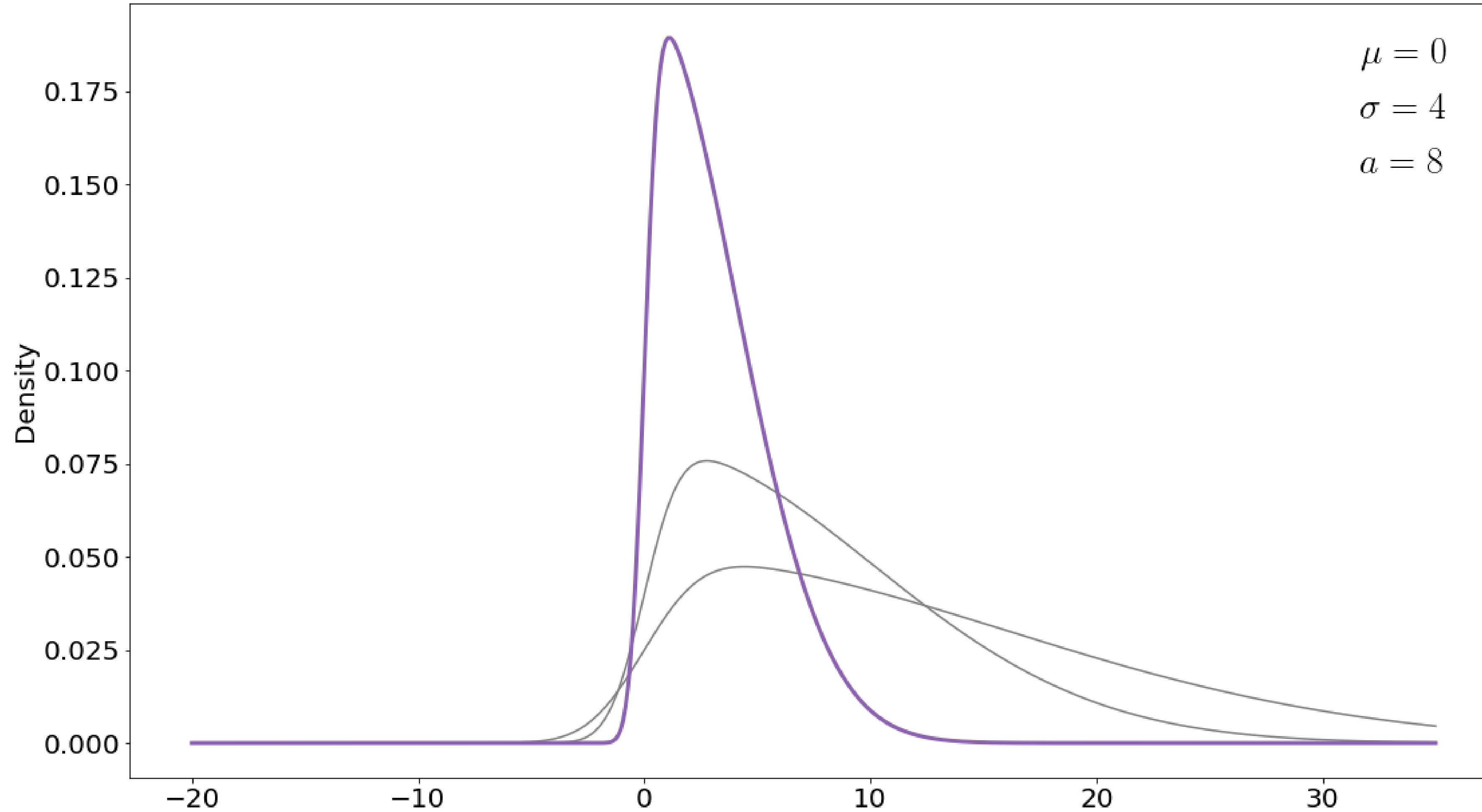
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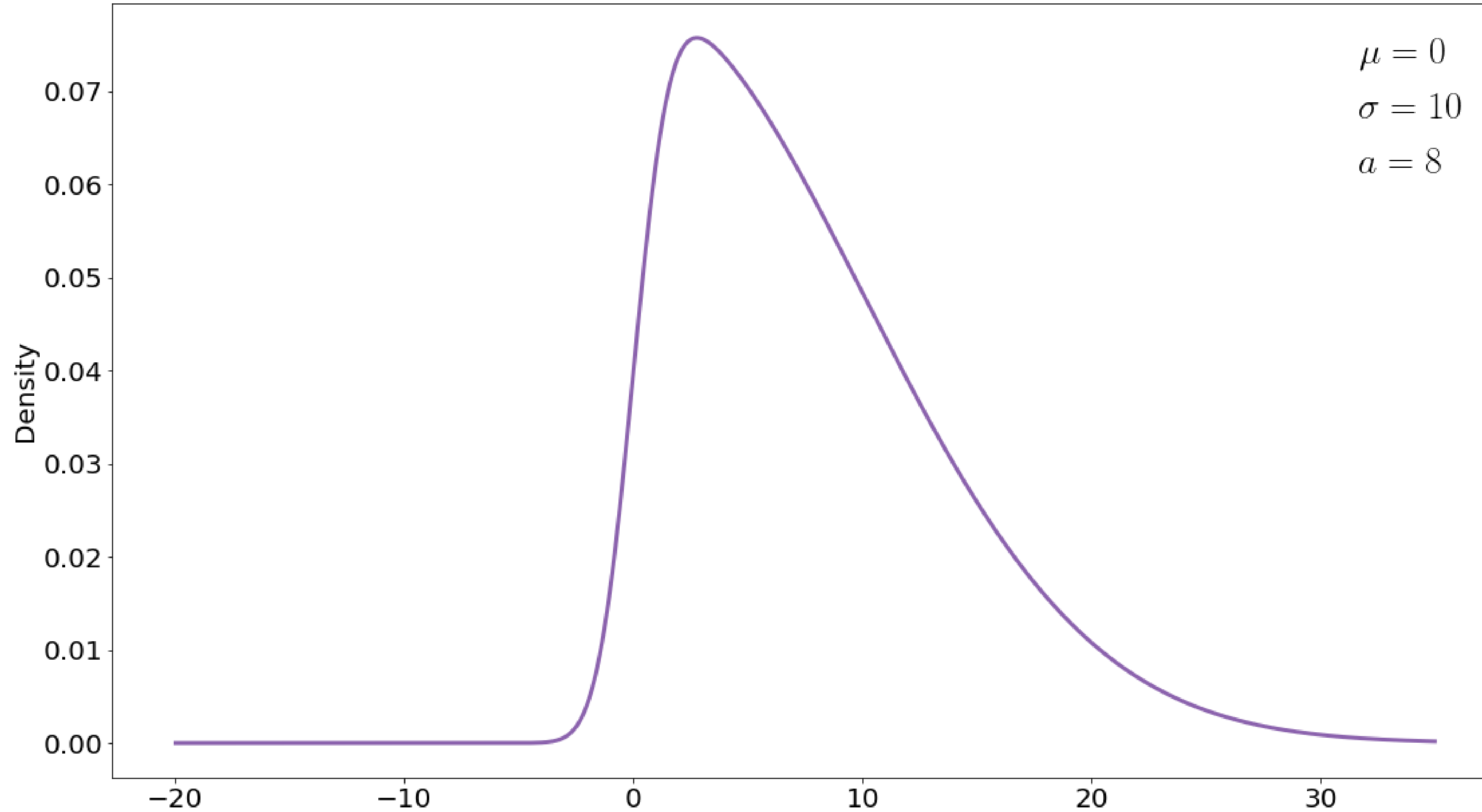
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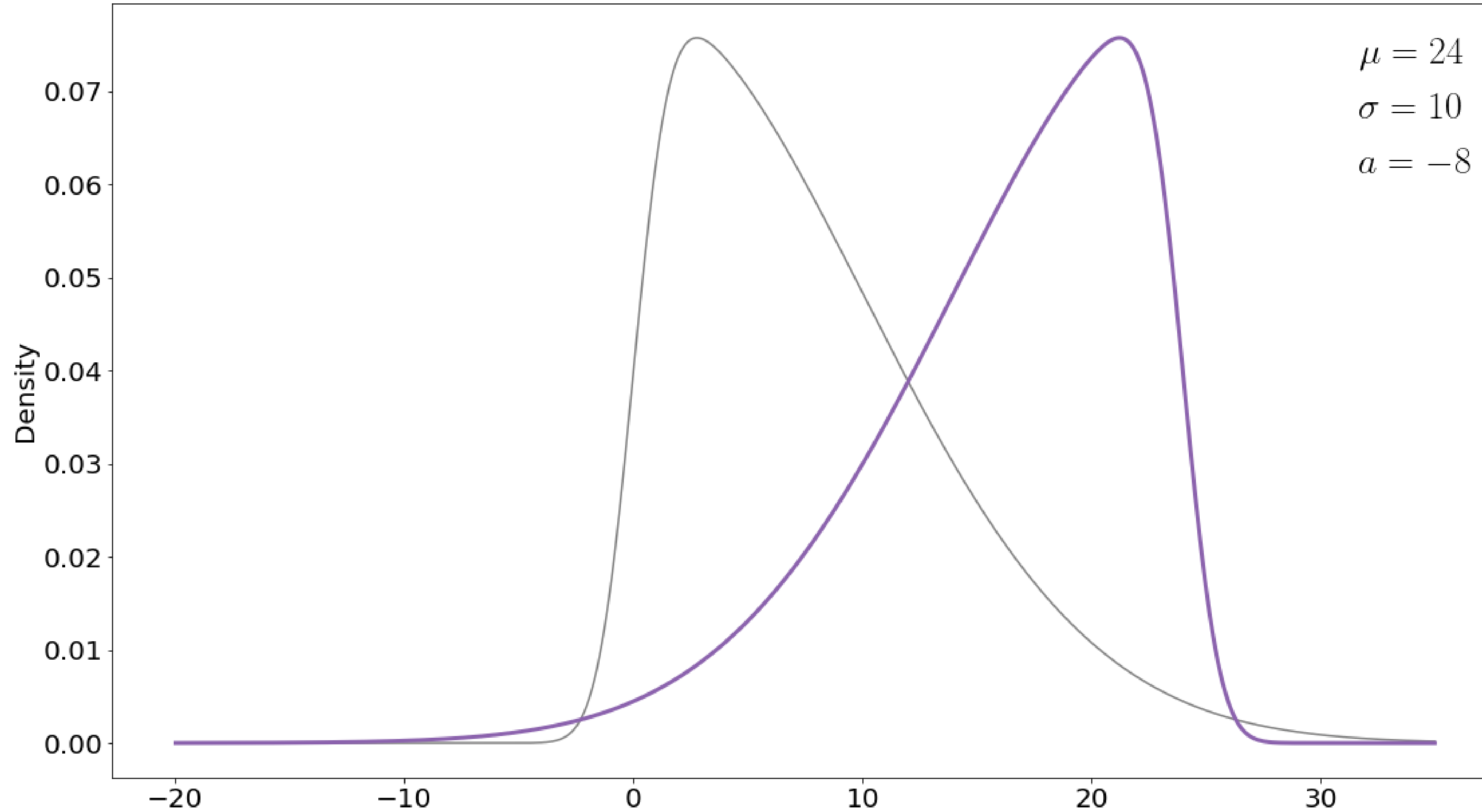
Skewness Parameter

$$f(x) = \frac{\varphi\left(\frac{x-\mu}{\sigma}\right)\Phi\left(a\frac{x-\mu}{\sigma}\right)}{\sigma\Phi(0)}$$



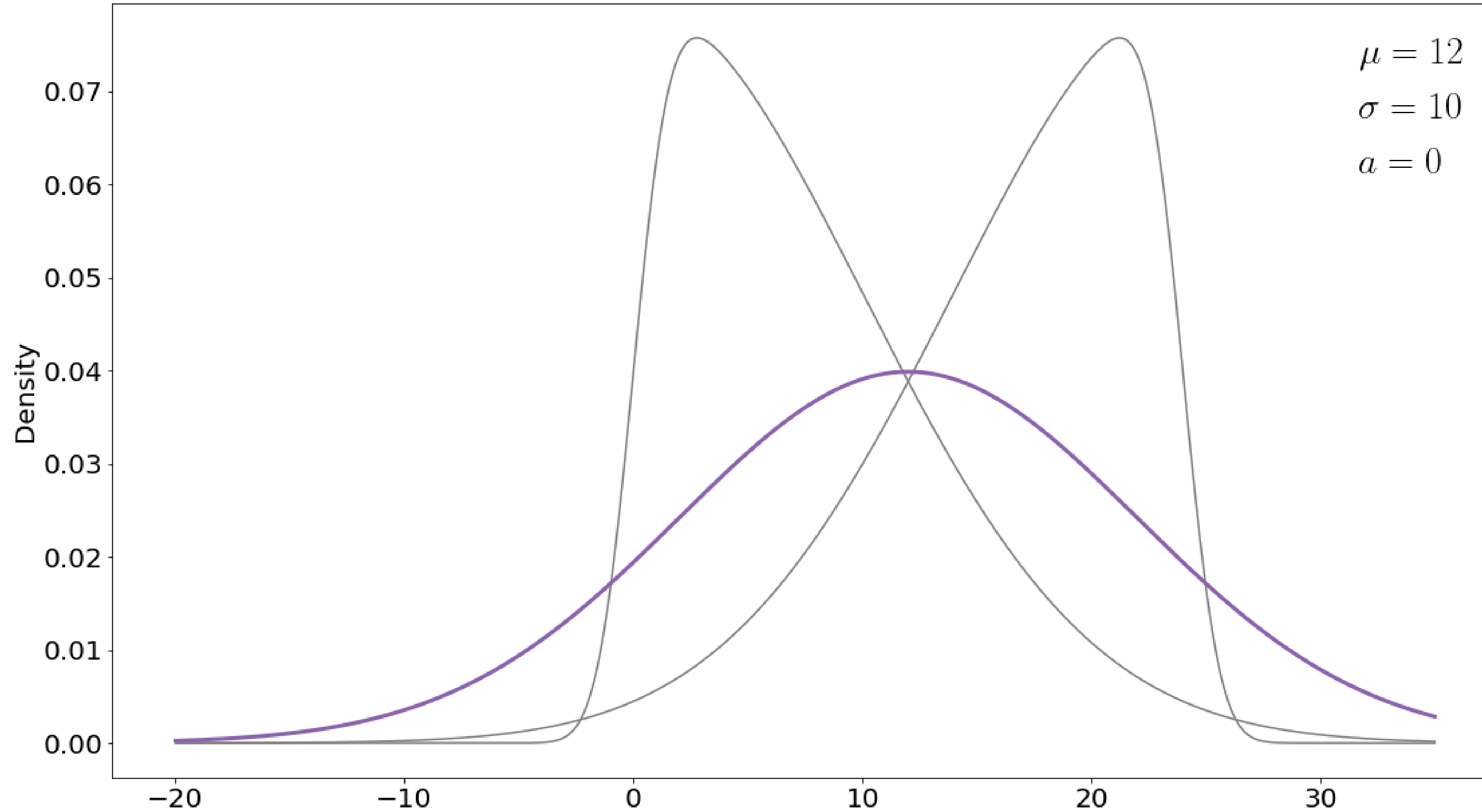
Scale Parameter

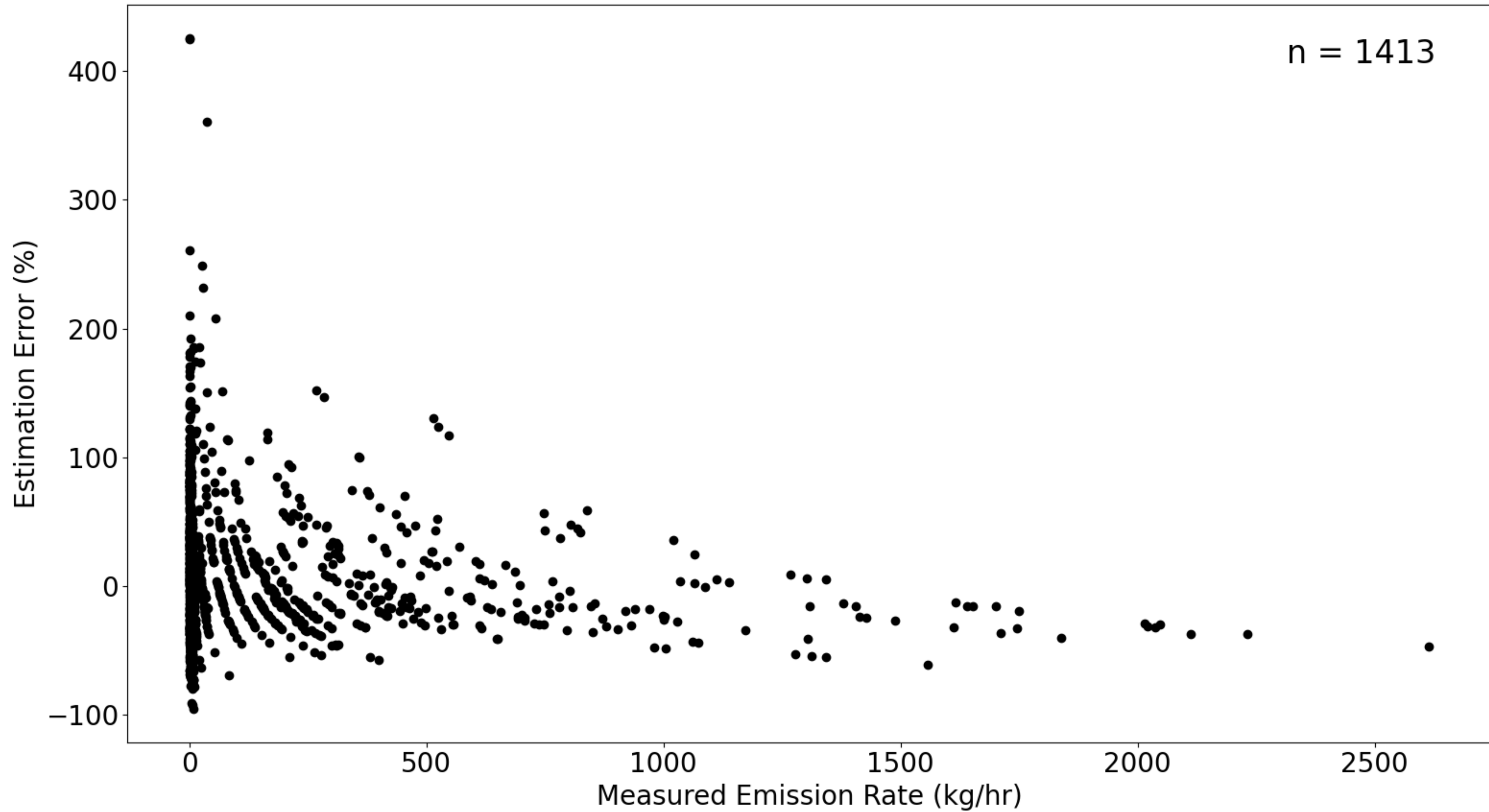
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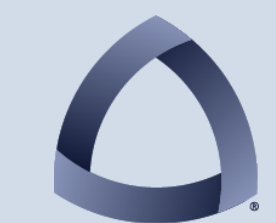
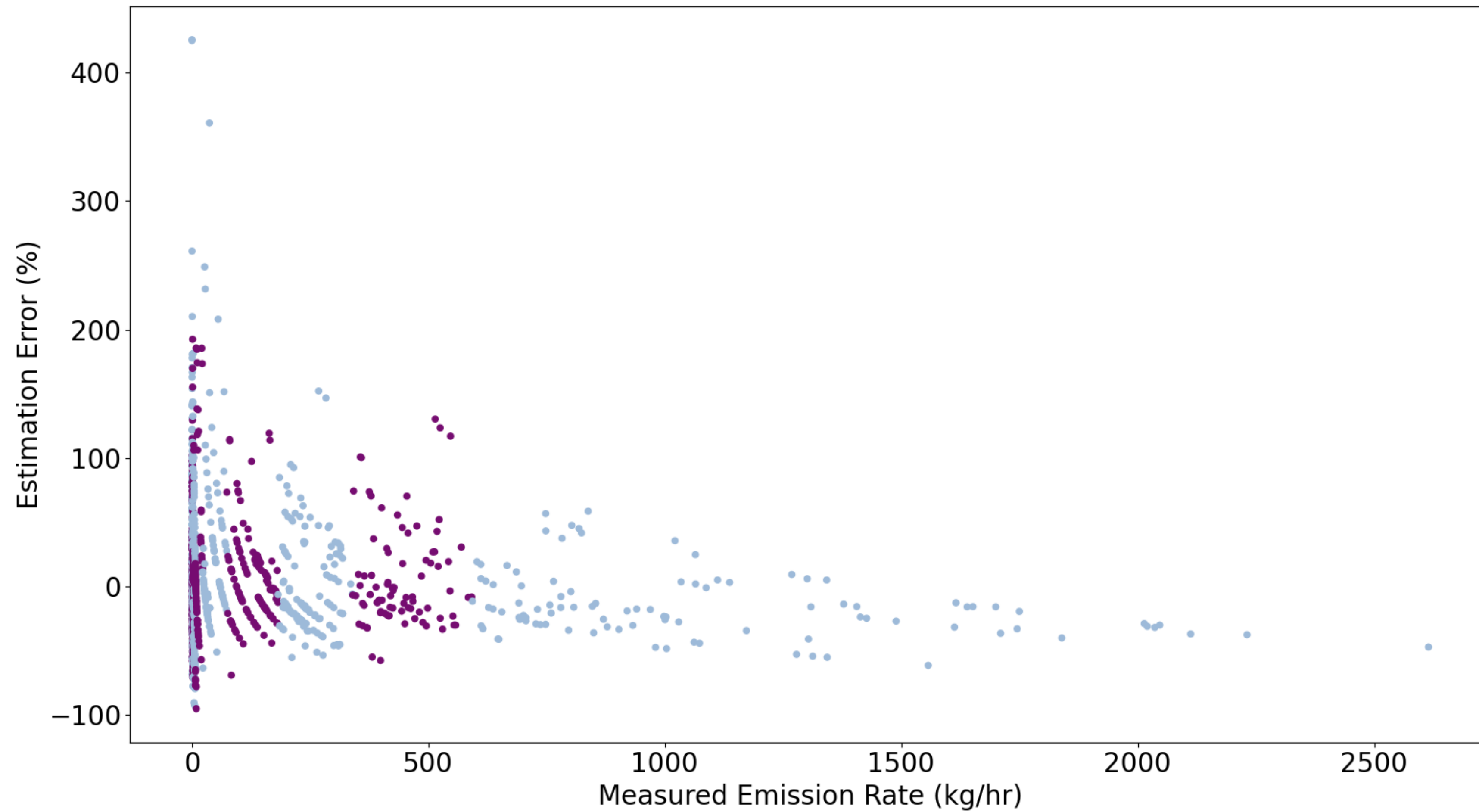
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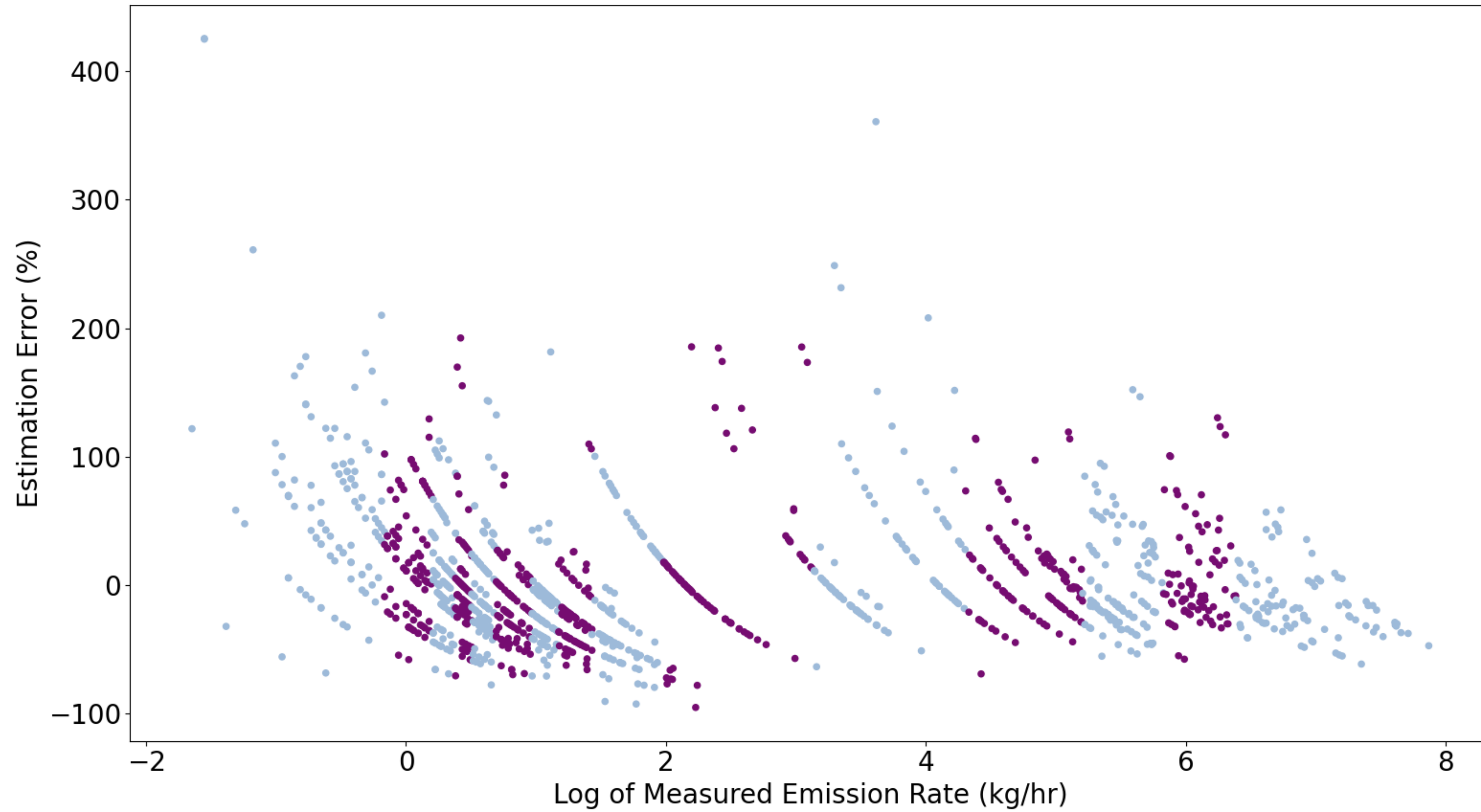




Method 1: Binning

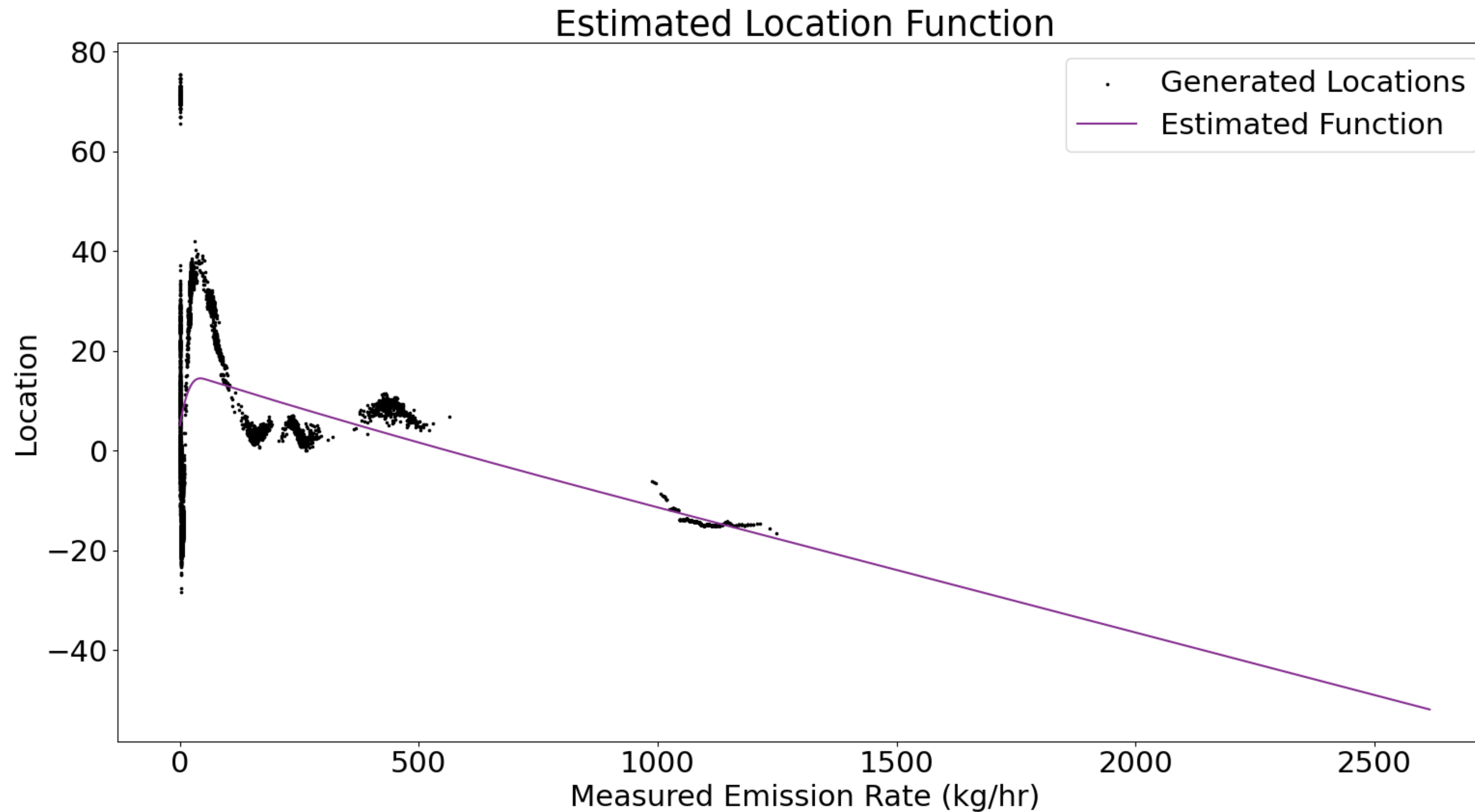


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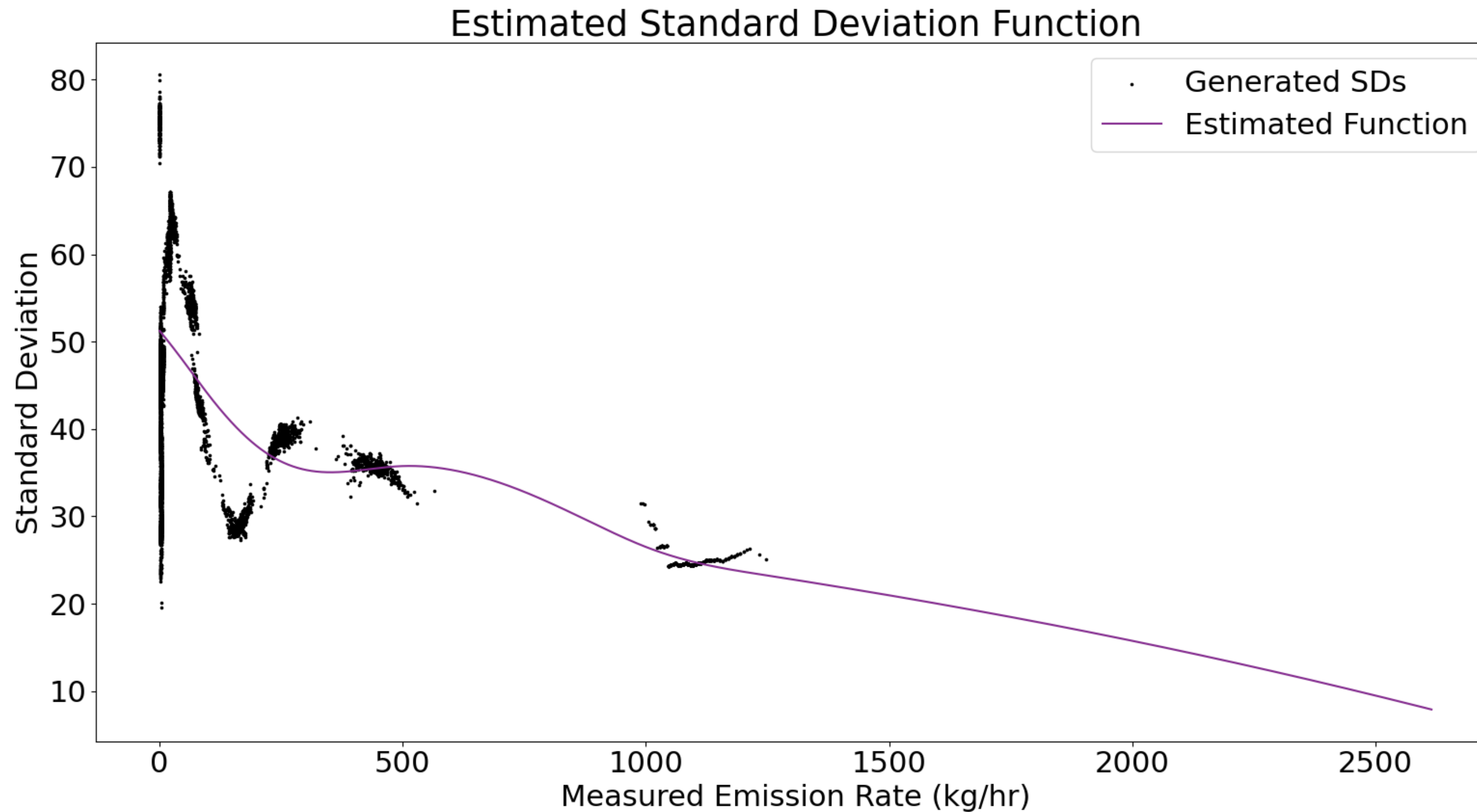
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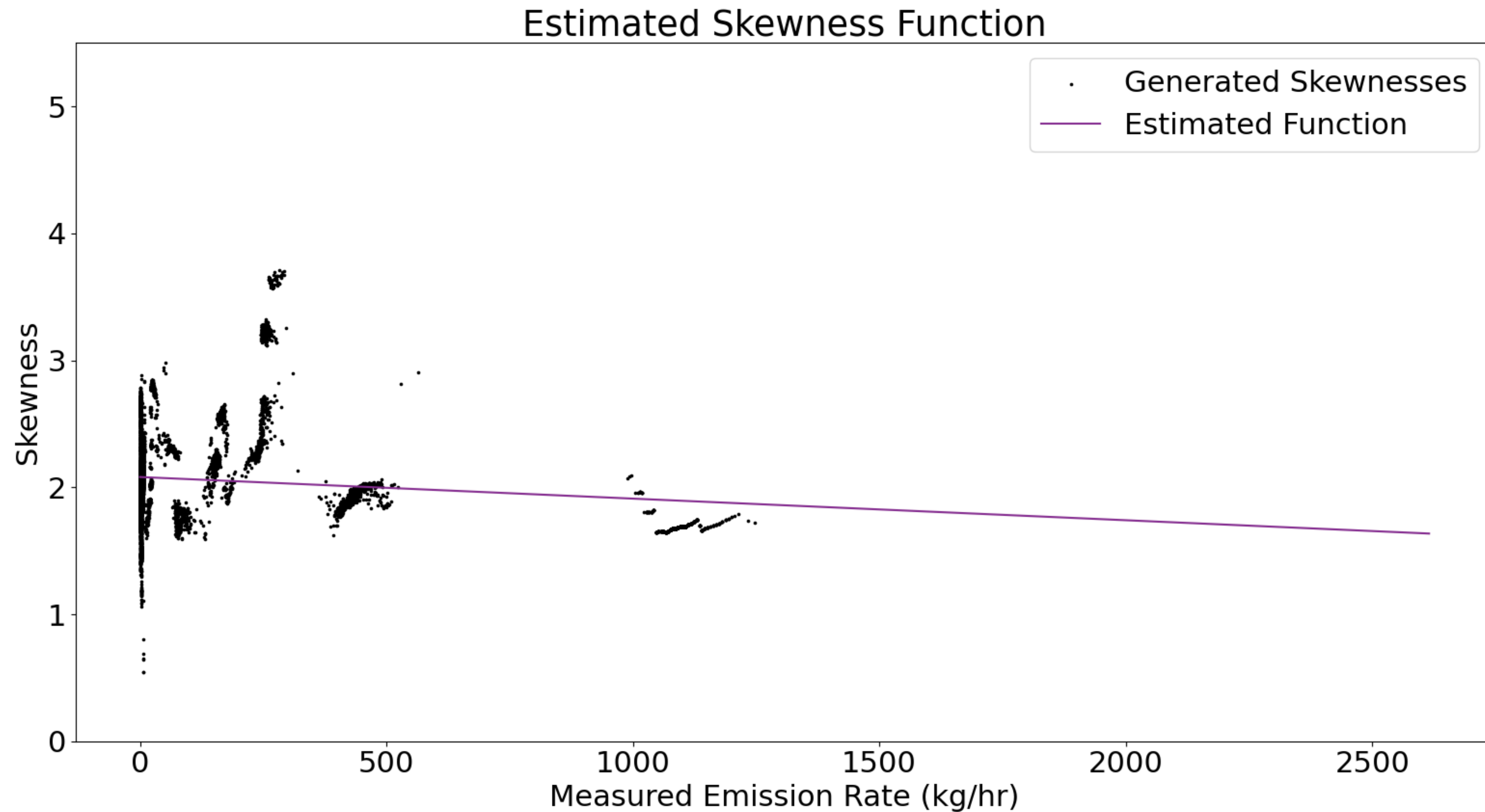
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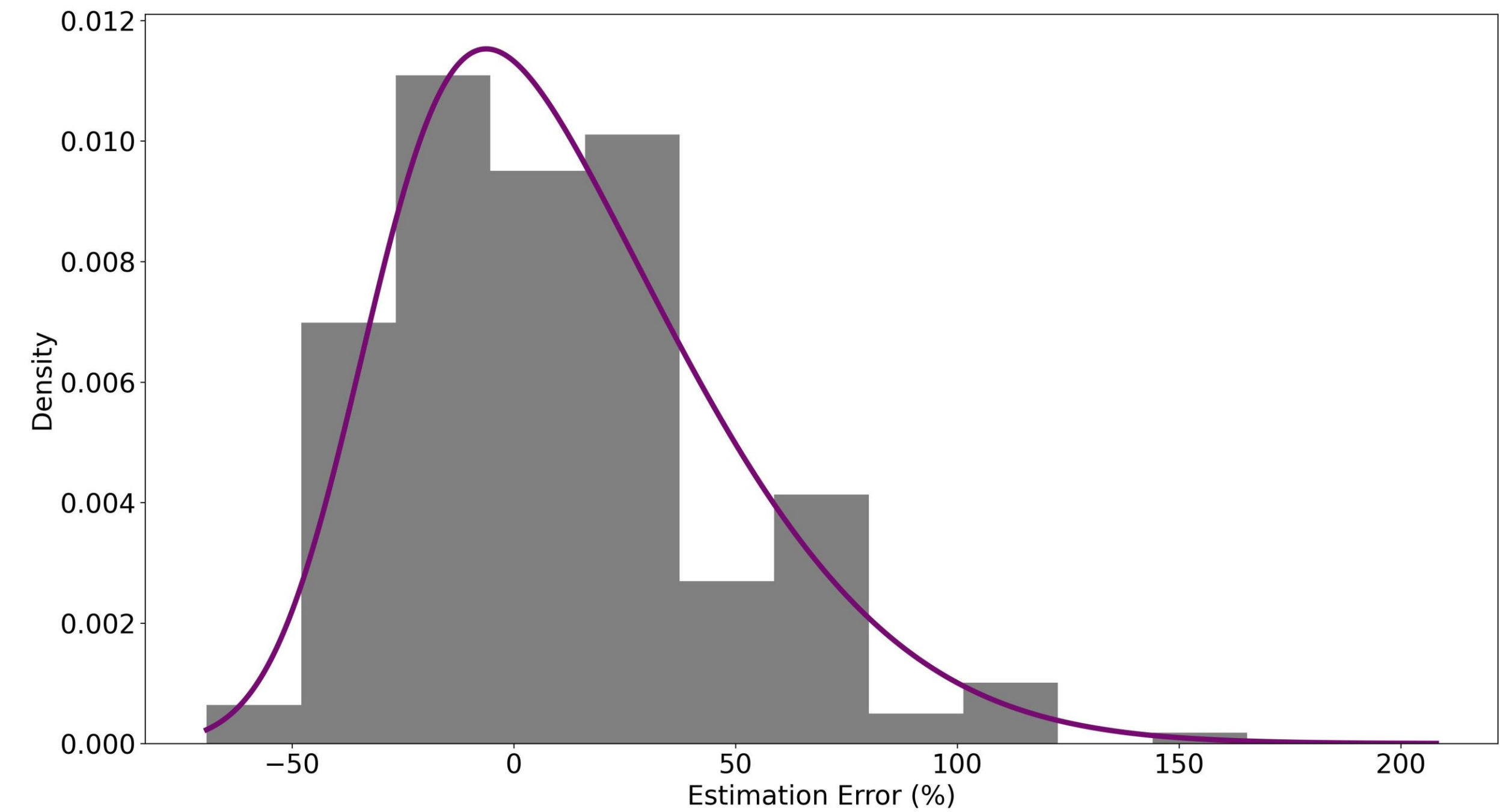
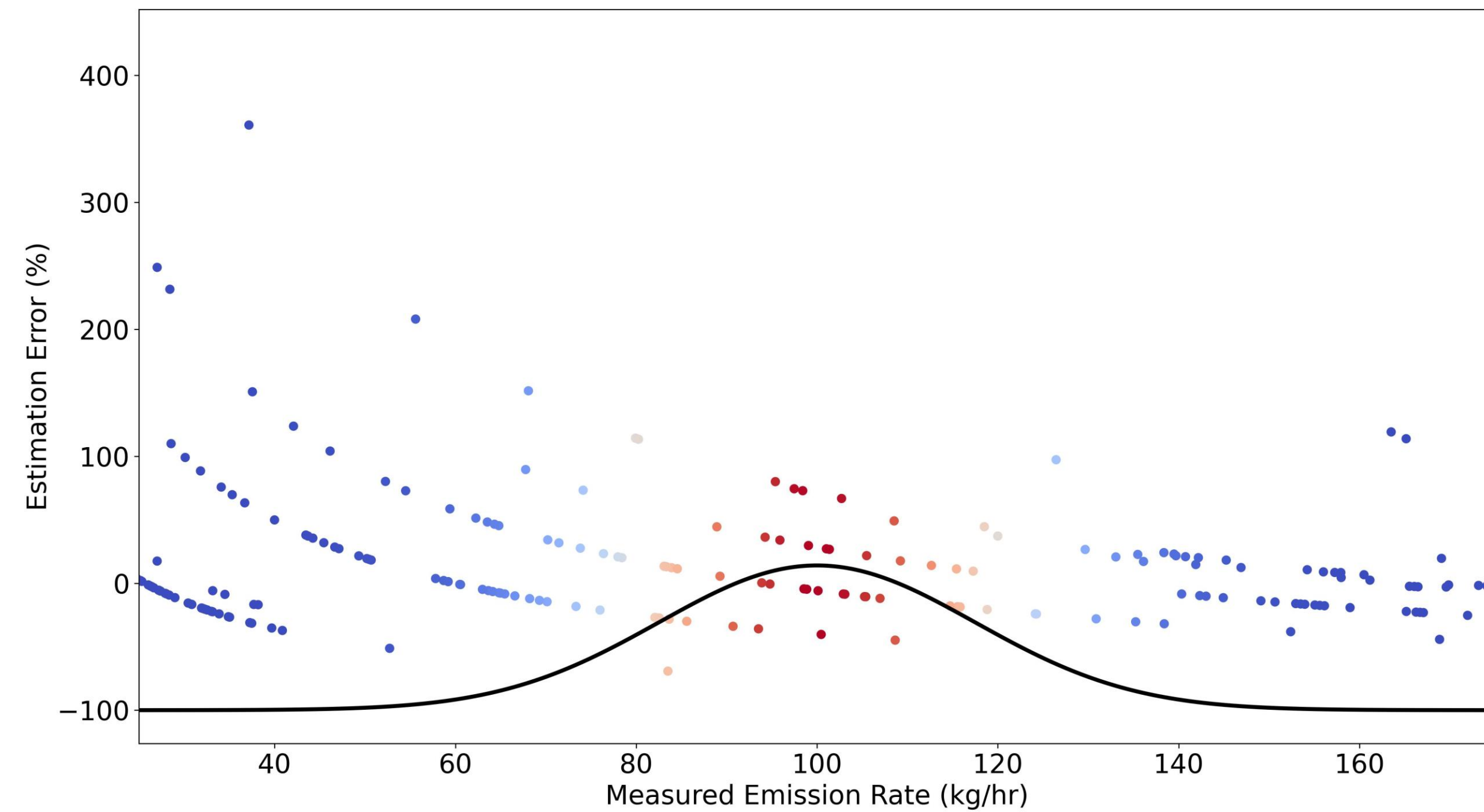


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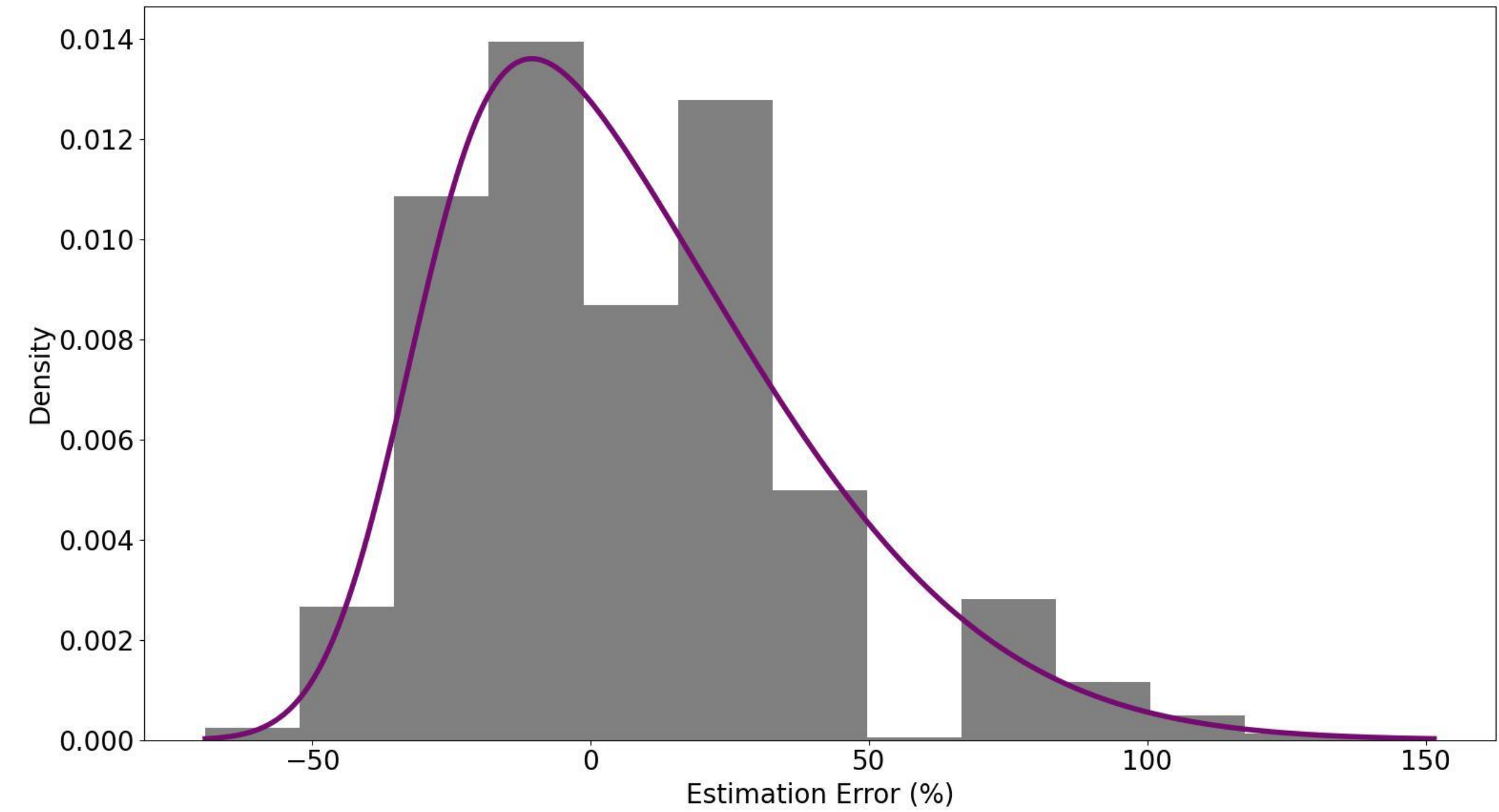
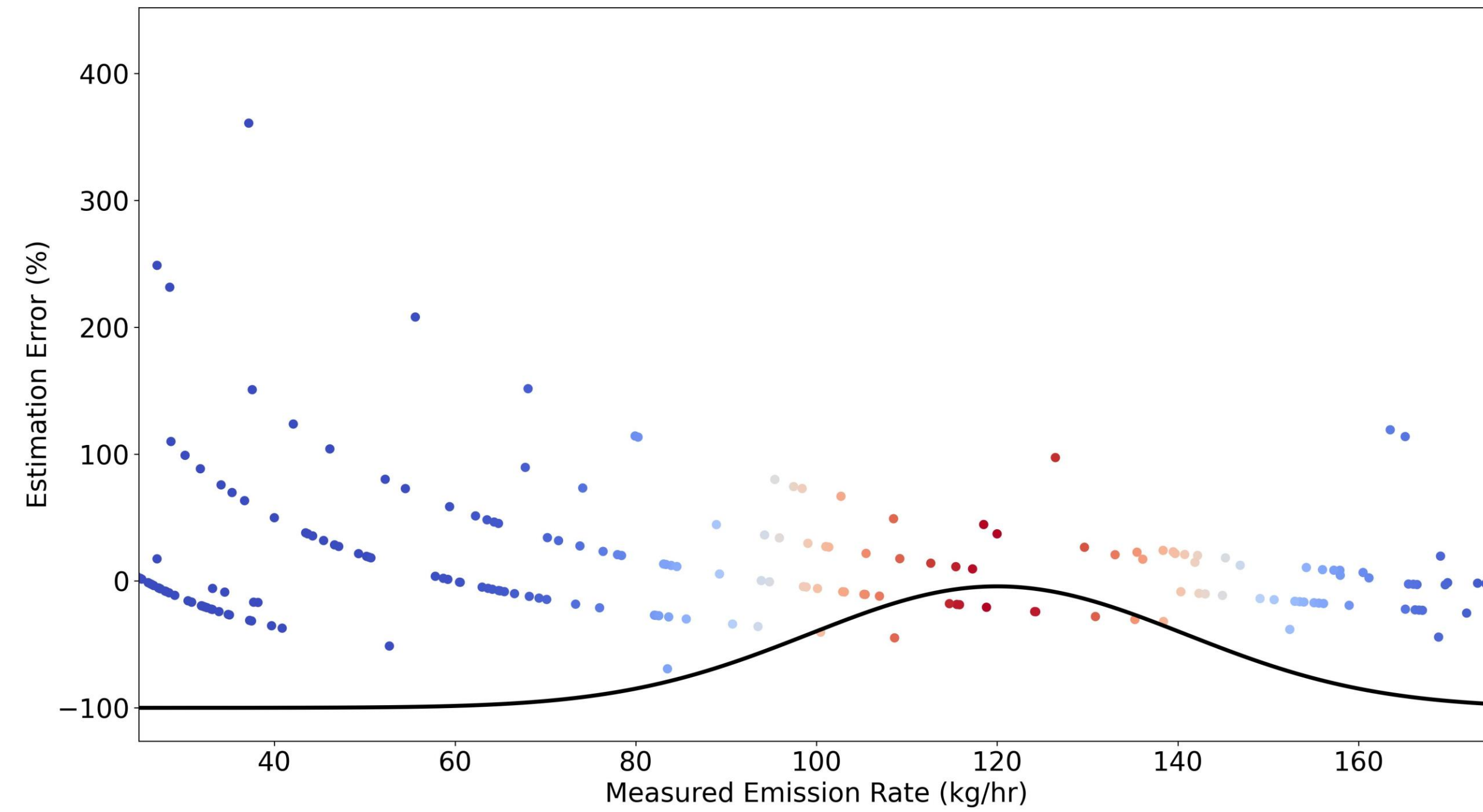
$$f(x) = \frac{\varphi\left(\frac{x-\mu}{\sigma}\right)\Phi\left(a\frac{x-\mu}{\sigma}\right)}{\sigma\Phi(0)}$$



Method 2: Kernel-Based

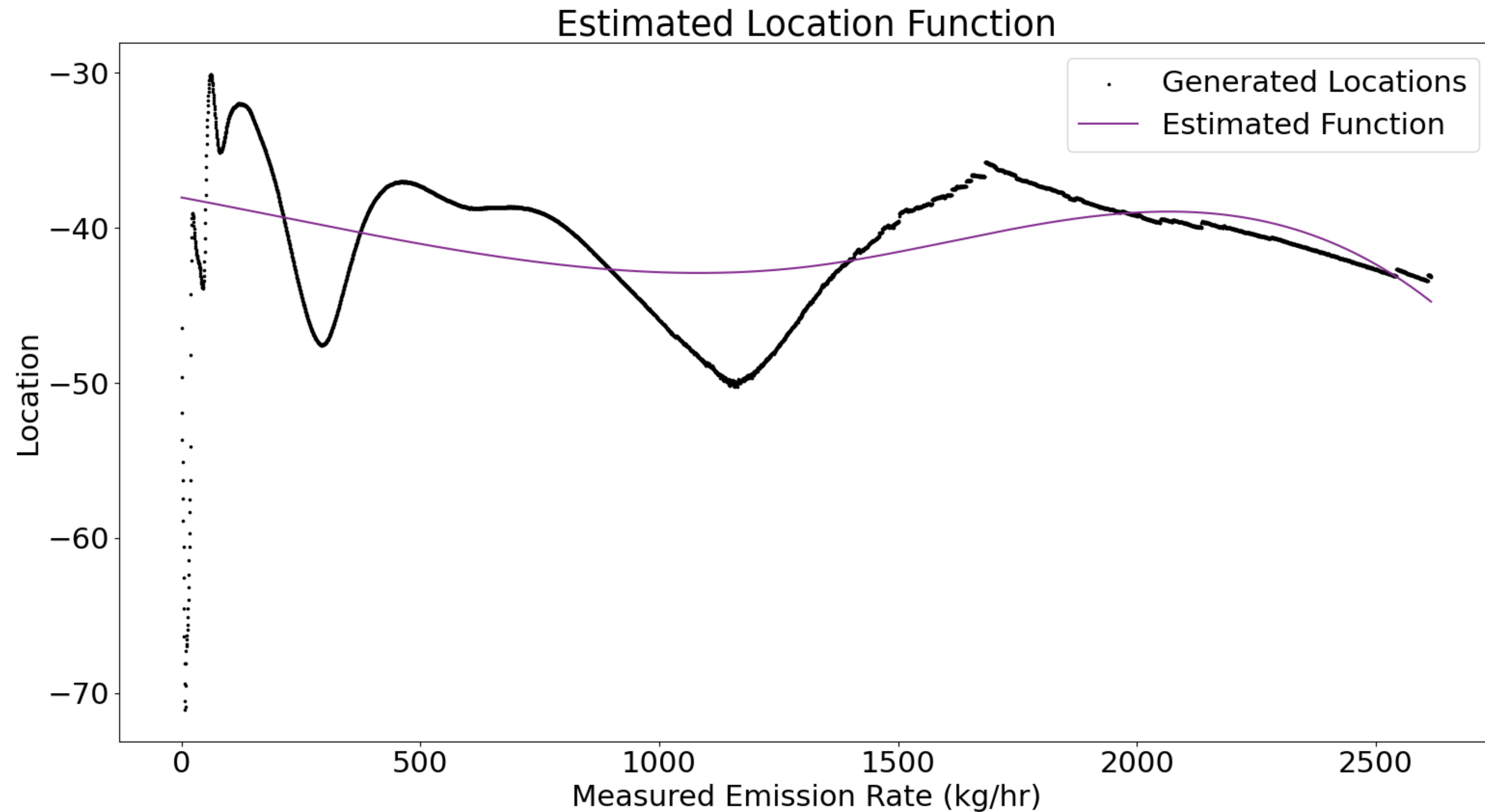


Method 2: Kernel-Based



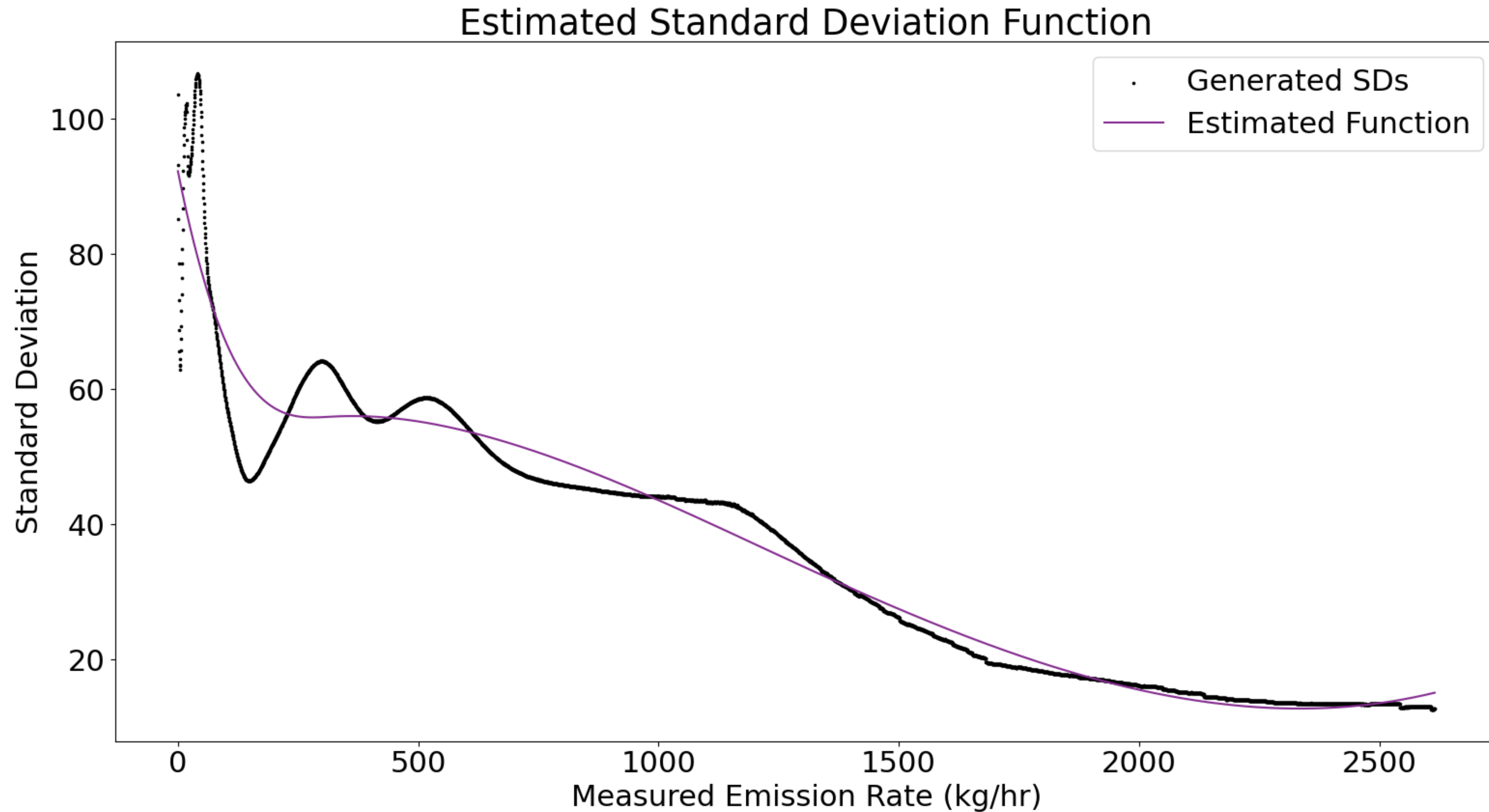
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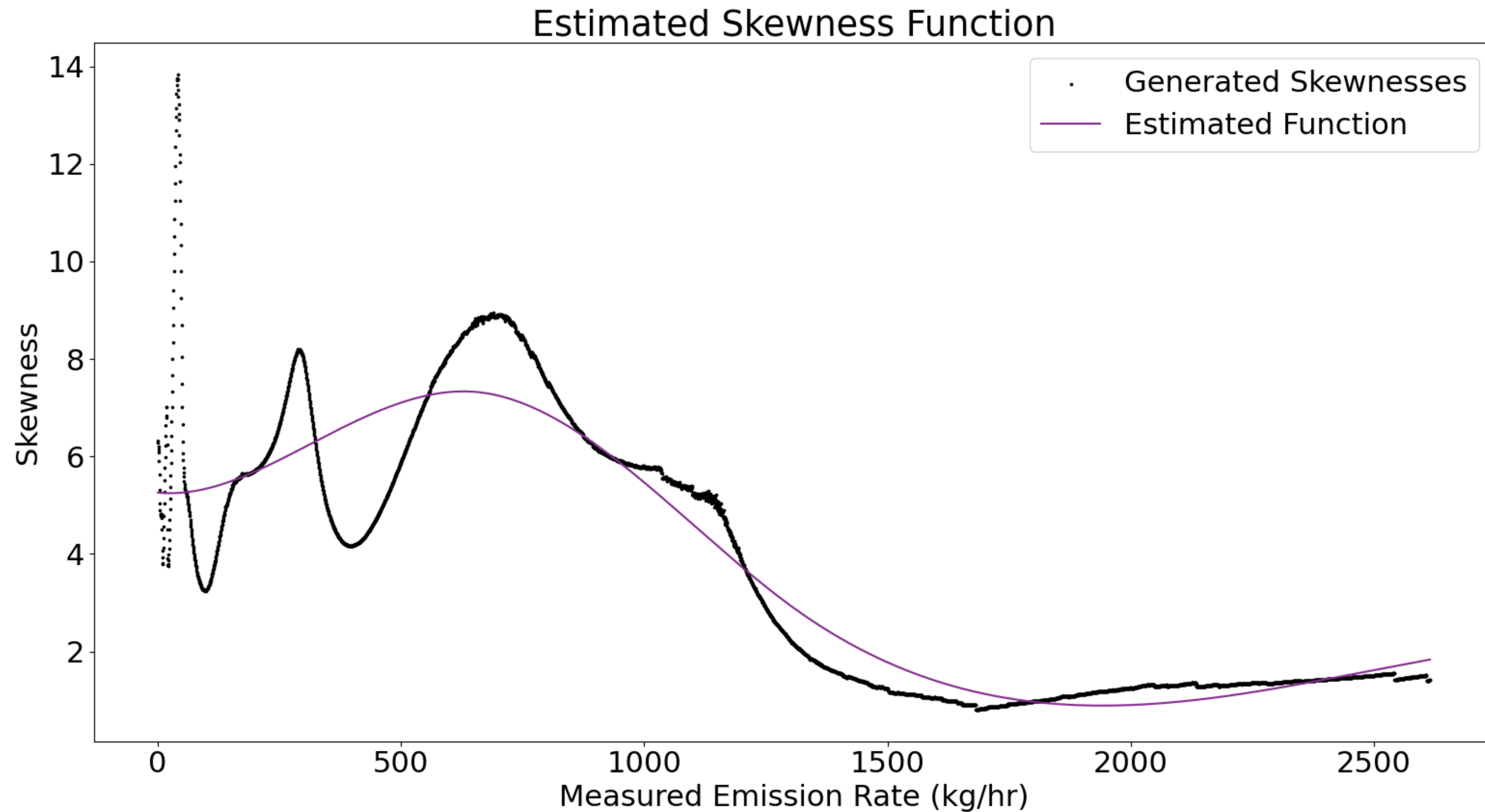
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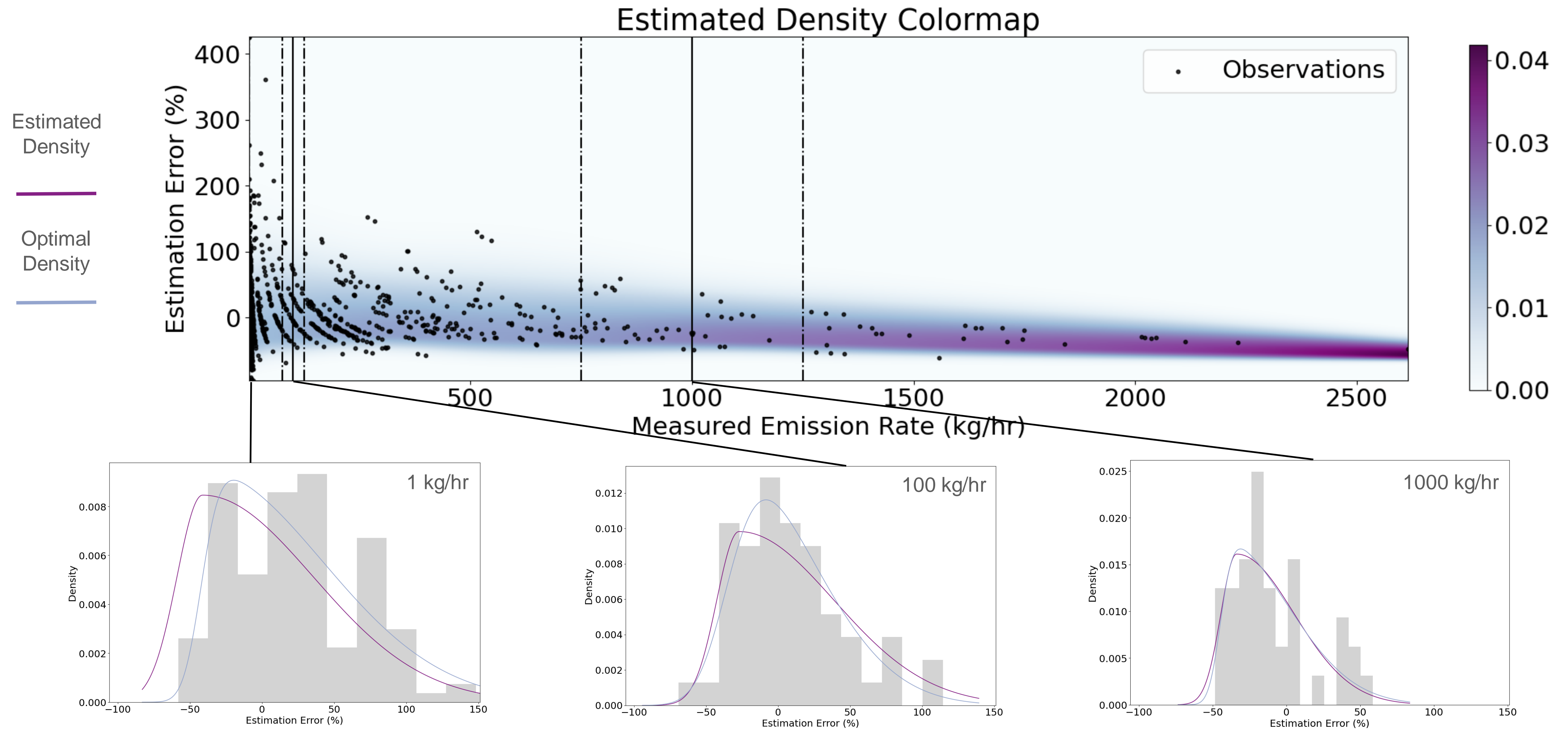


Framework Output

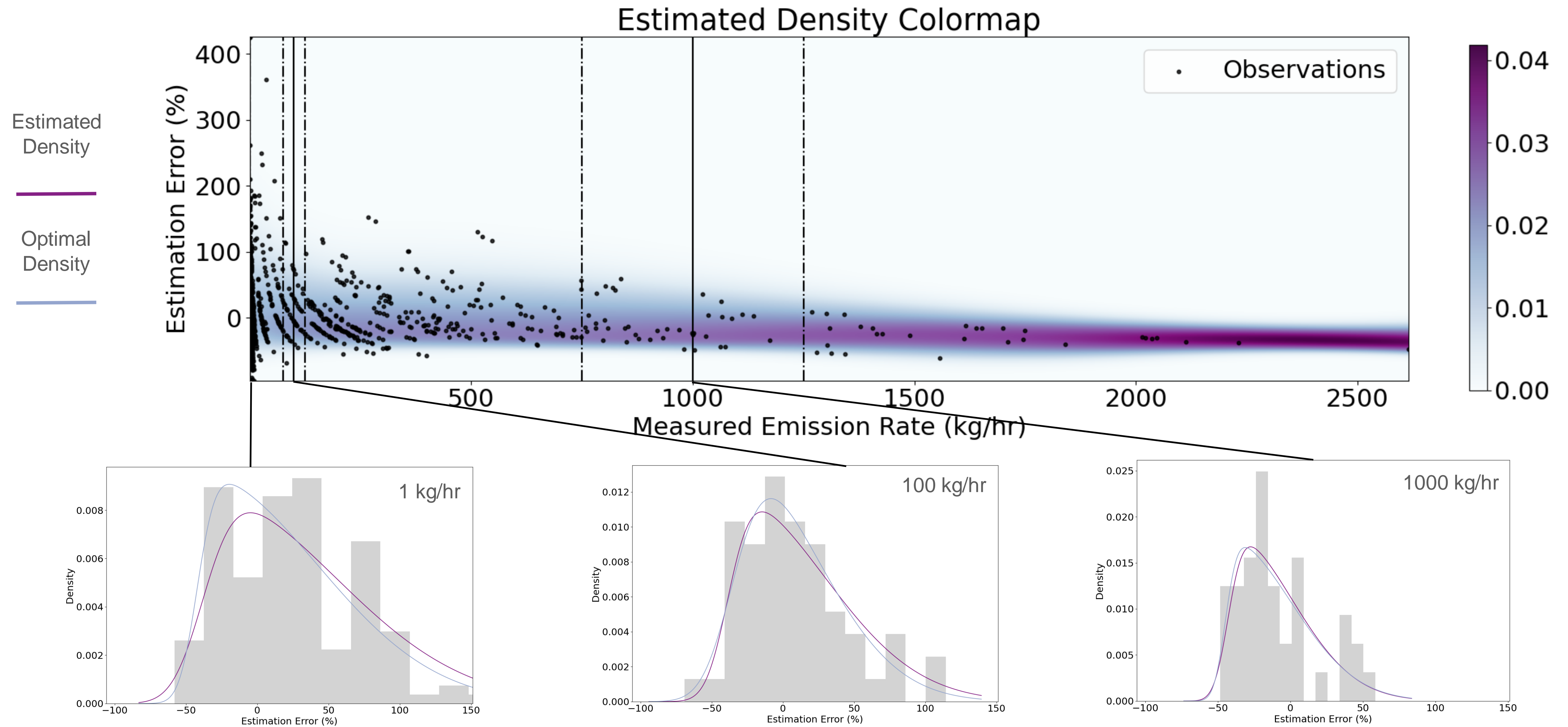
$$f(x) = \frac{\varphi\left(\frac{x-\mu}{\sigma}\right)\Phi\left(a\frac{x-\mu}{\sigma}\right)}{\sigma\Phi(0)}$$

- Both methods generate 3 functions (of measured emission rate):
 - ▶ Location
 - ▶ Standard Deviation
 - ▶ Skewness
- From these, a skew normal distribution can be generated for any value of measured emission rate

Method 1: Binning

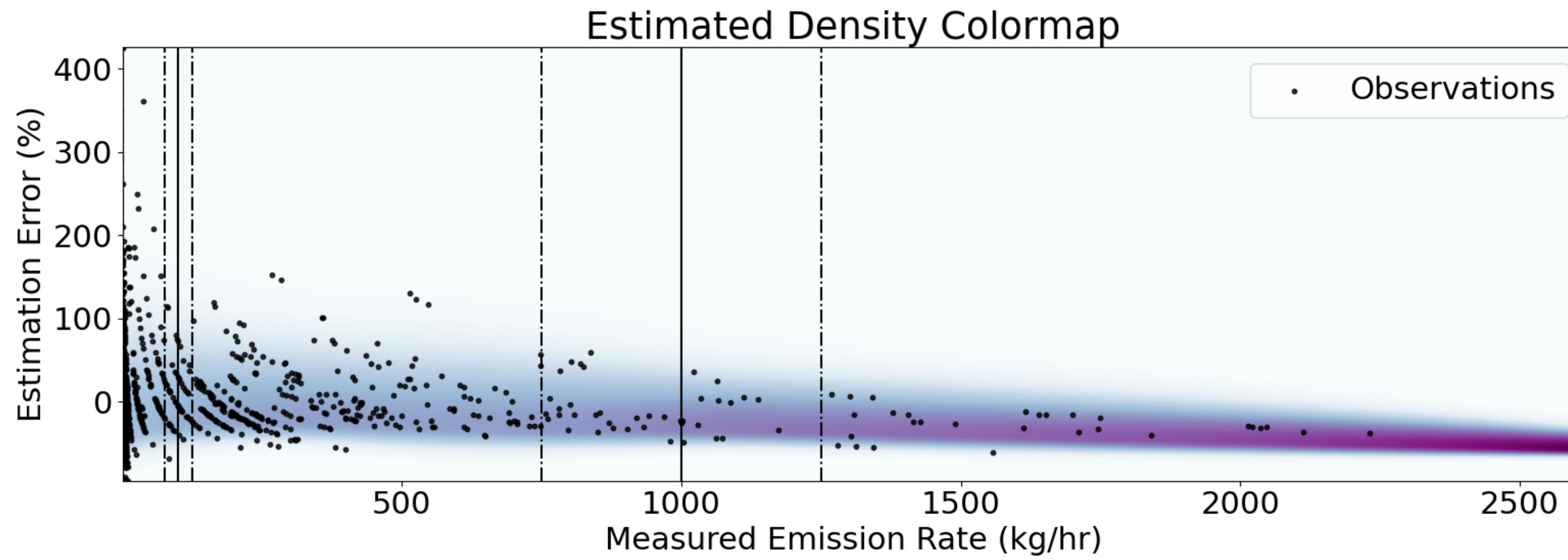


Method 2: Kernel-Based

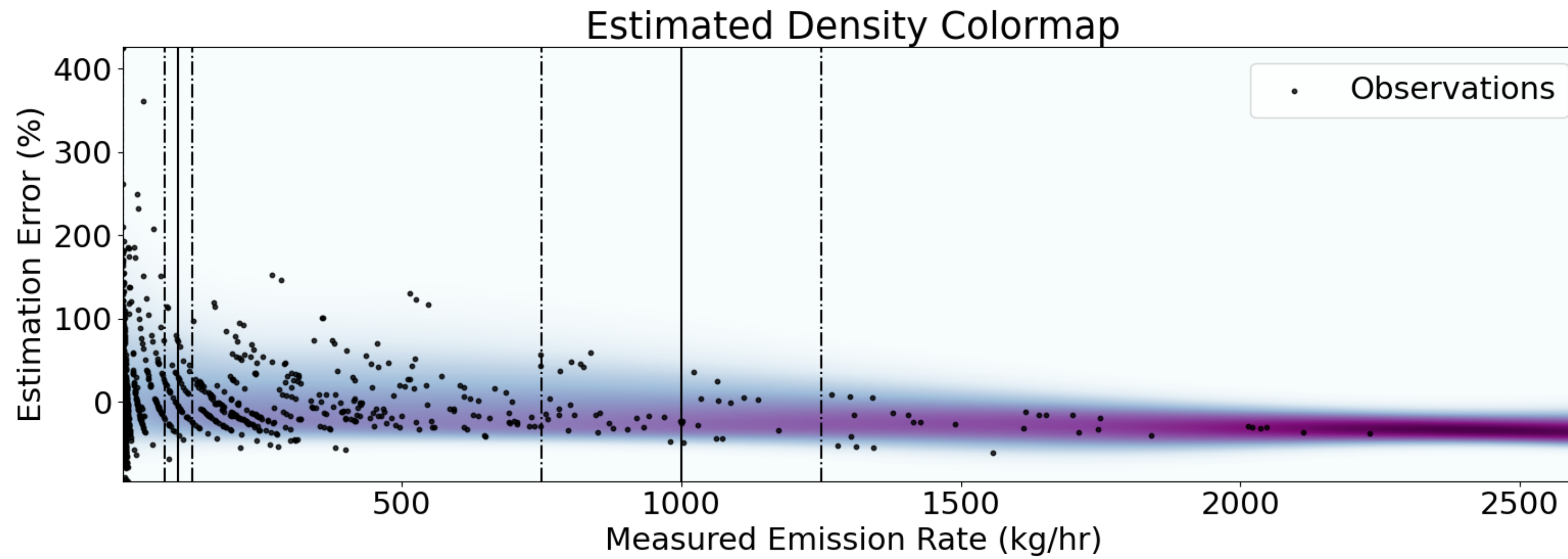


Comparison

Method 1:
Binning

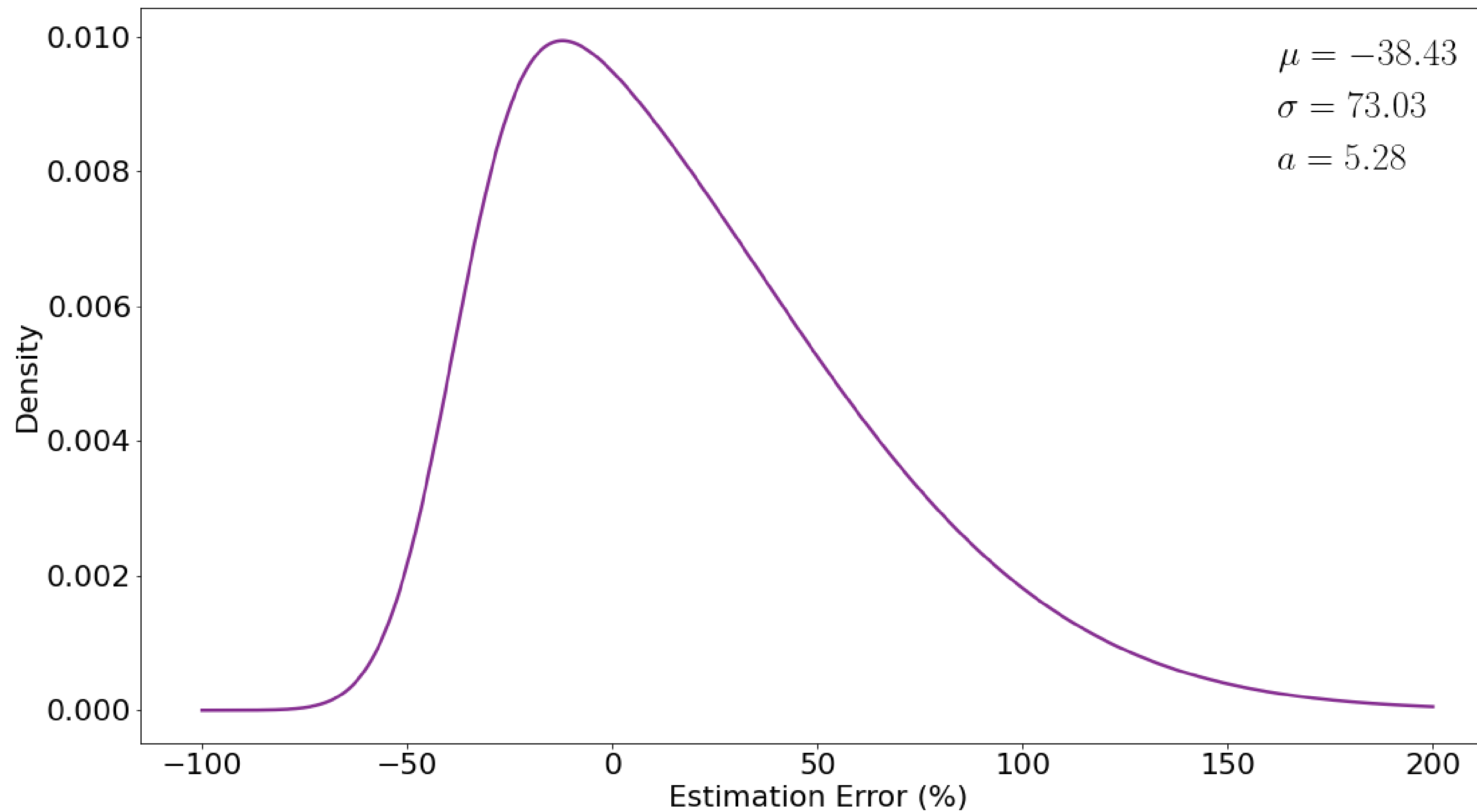


Method 2:
Kernel-Based



Use Example

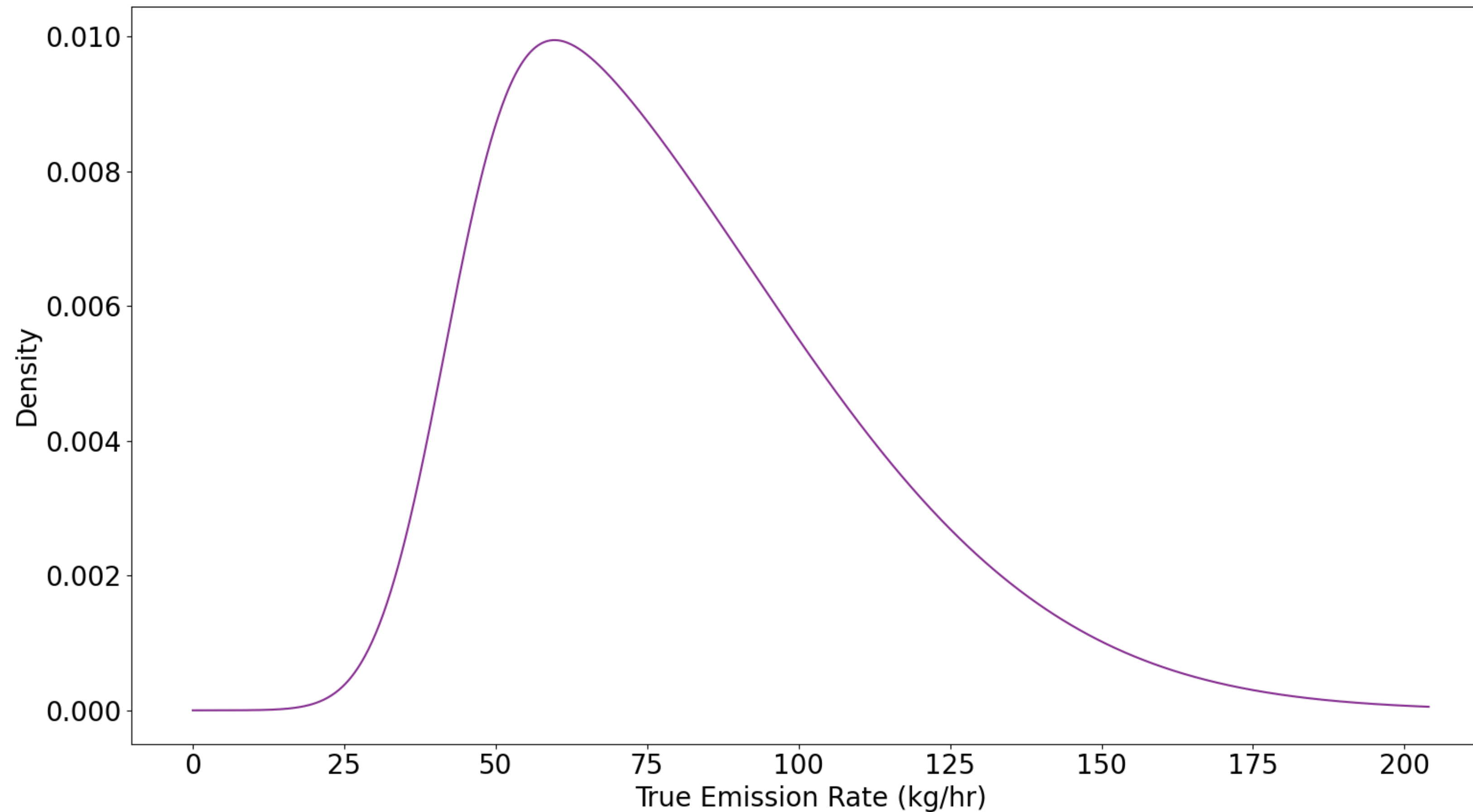
Measured Emission Rate = 68 kg/hr



Real-World Example

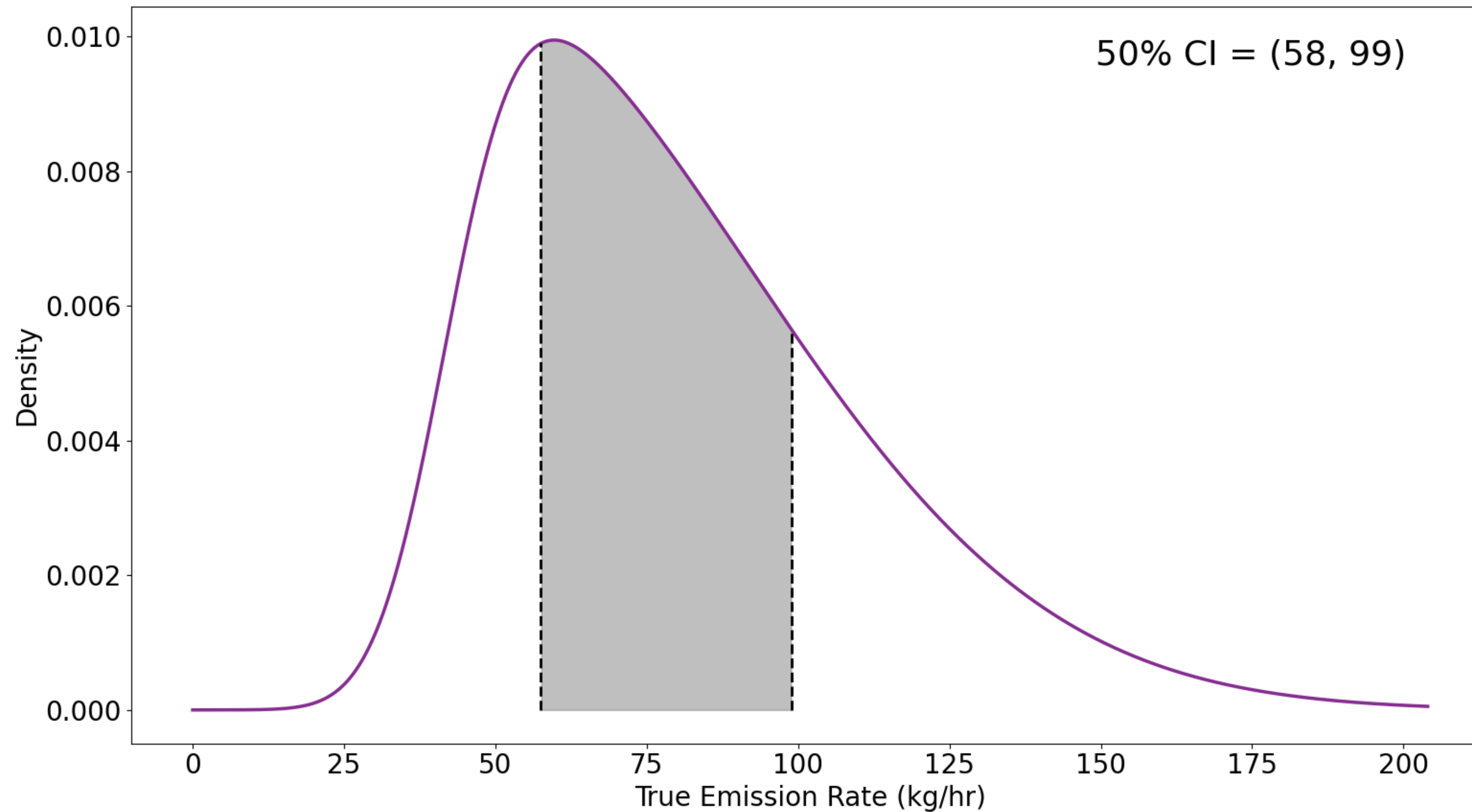
$$\text{Truth} = \text{Est.} \times \text{Est. Error} + \text{Est.}$$

Measured Emission Rate = 68 kg/hr



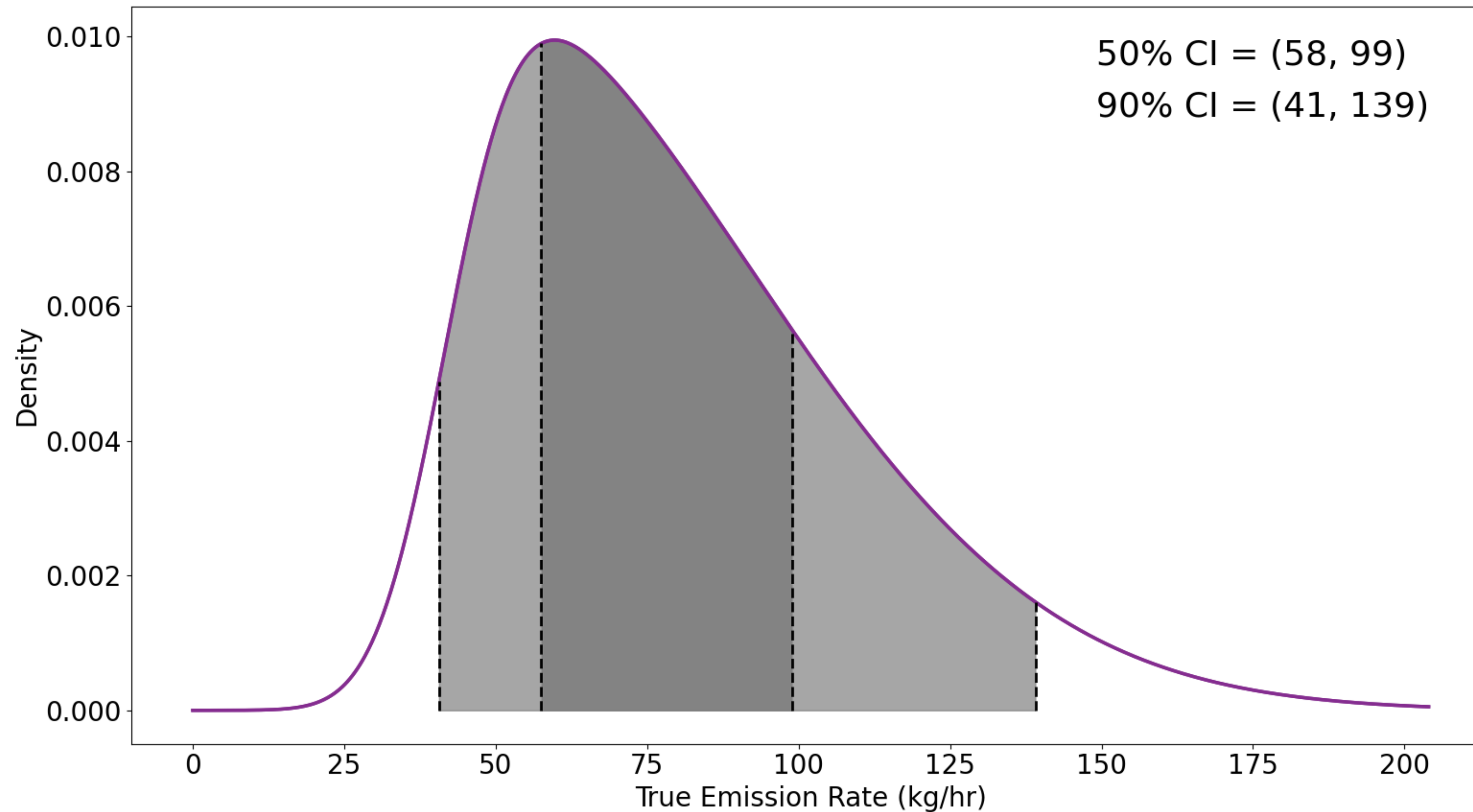
Use Example

Measured Emission Rate = 68 kg/hr



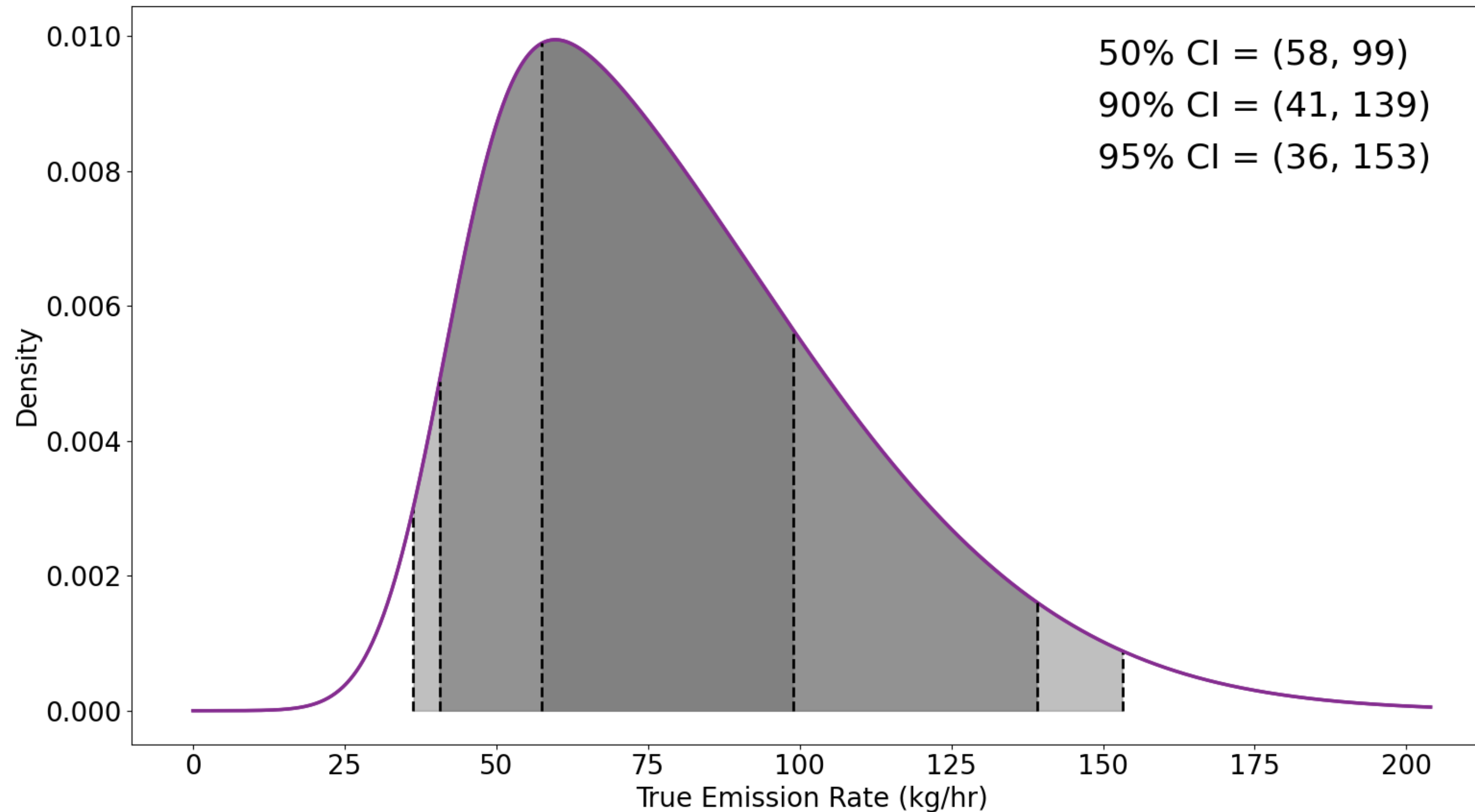
Use Example

Measured Emission Rate = 68 kg/hr



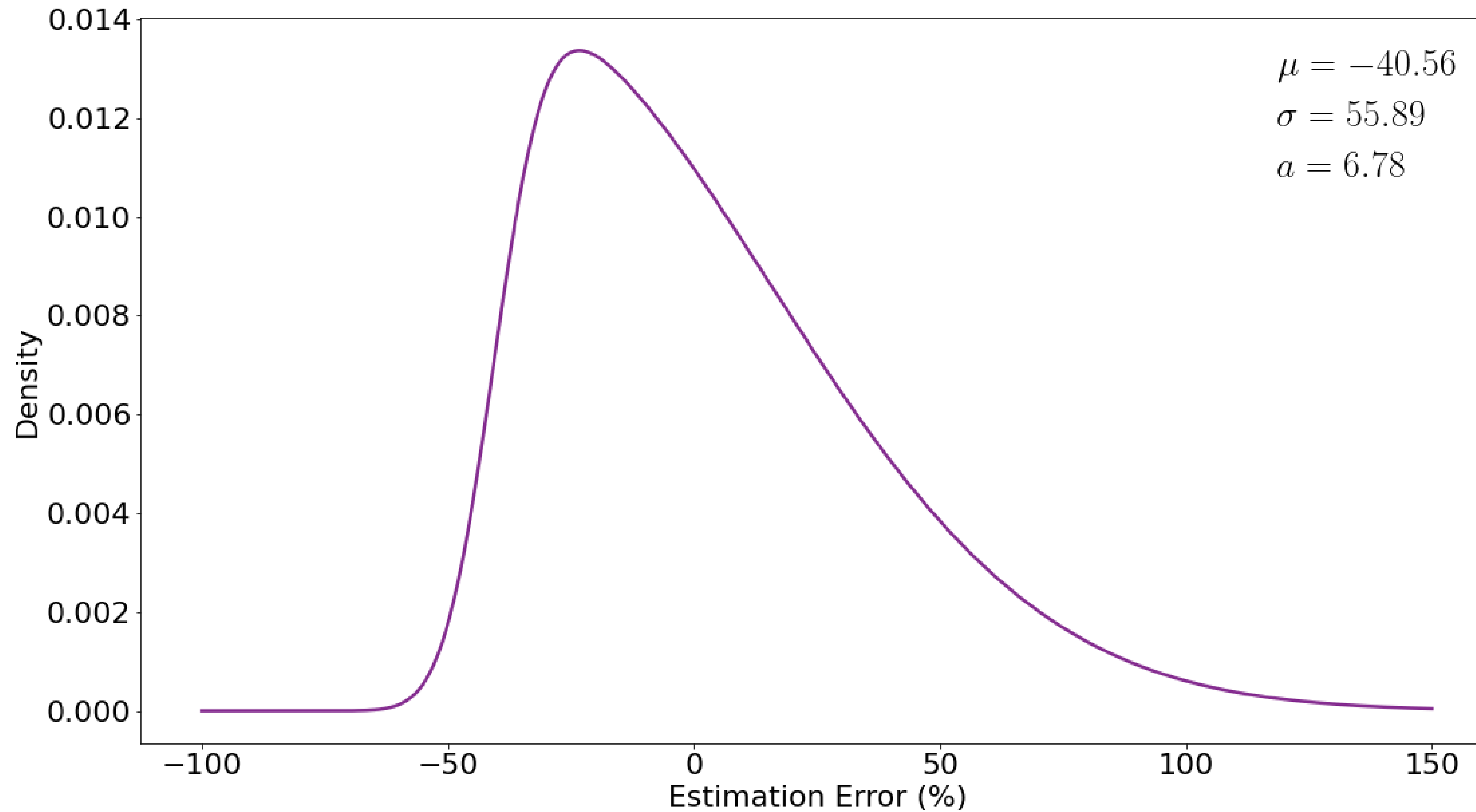
Use Example

Measured Emission Rate = 68 kg/hr



Use Example

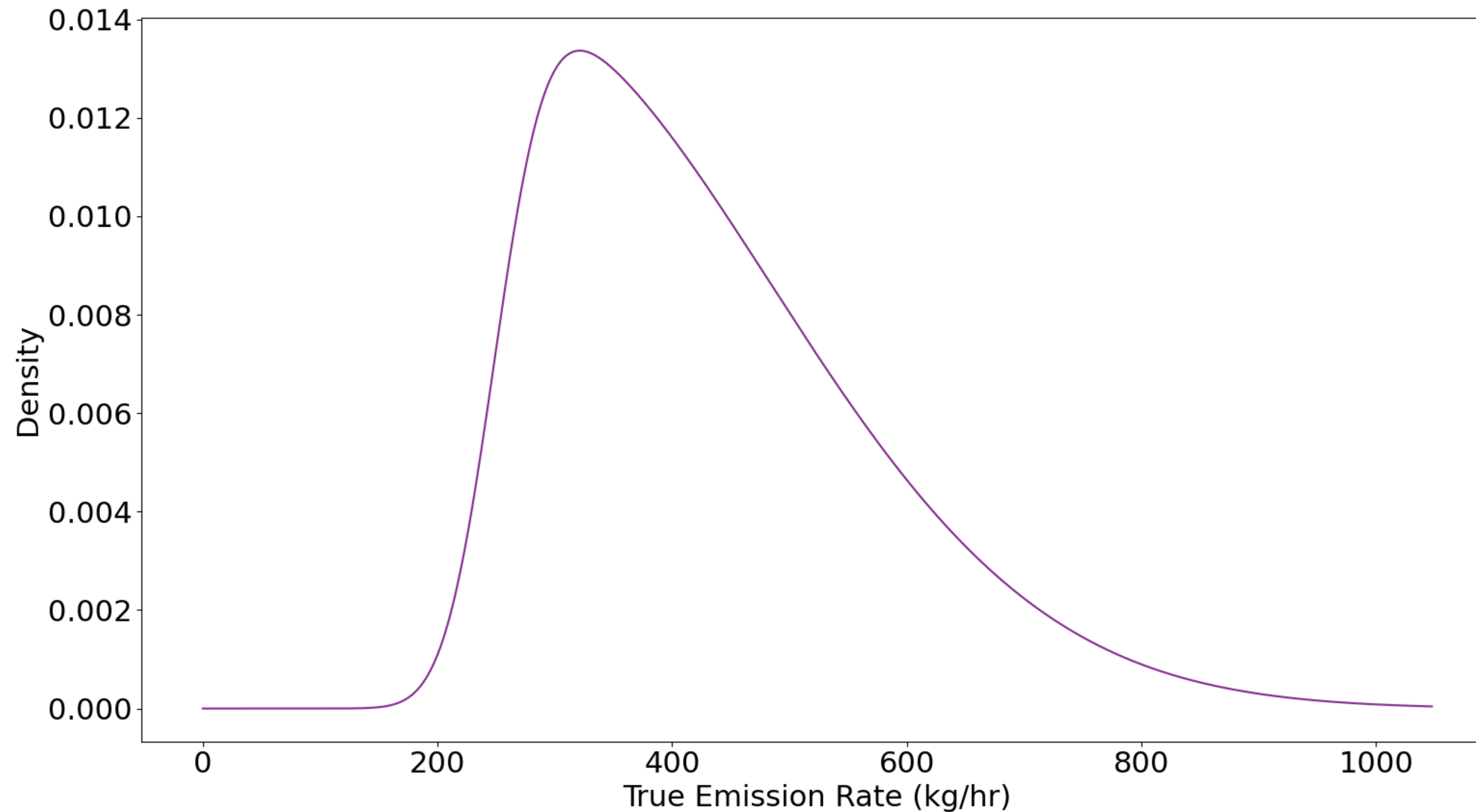
Measured Emission Rate = 419 kg/hr



Real-World Example

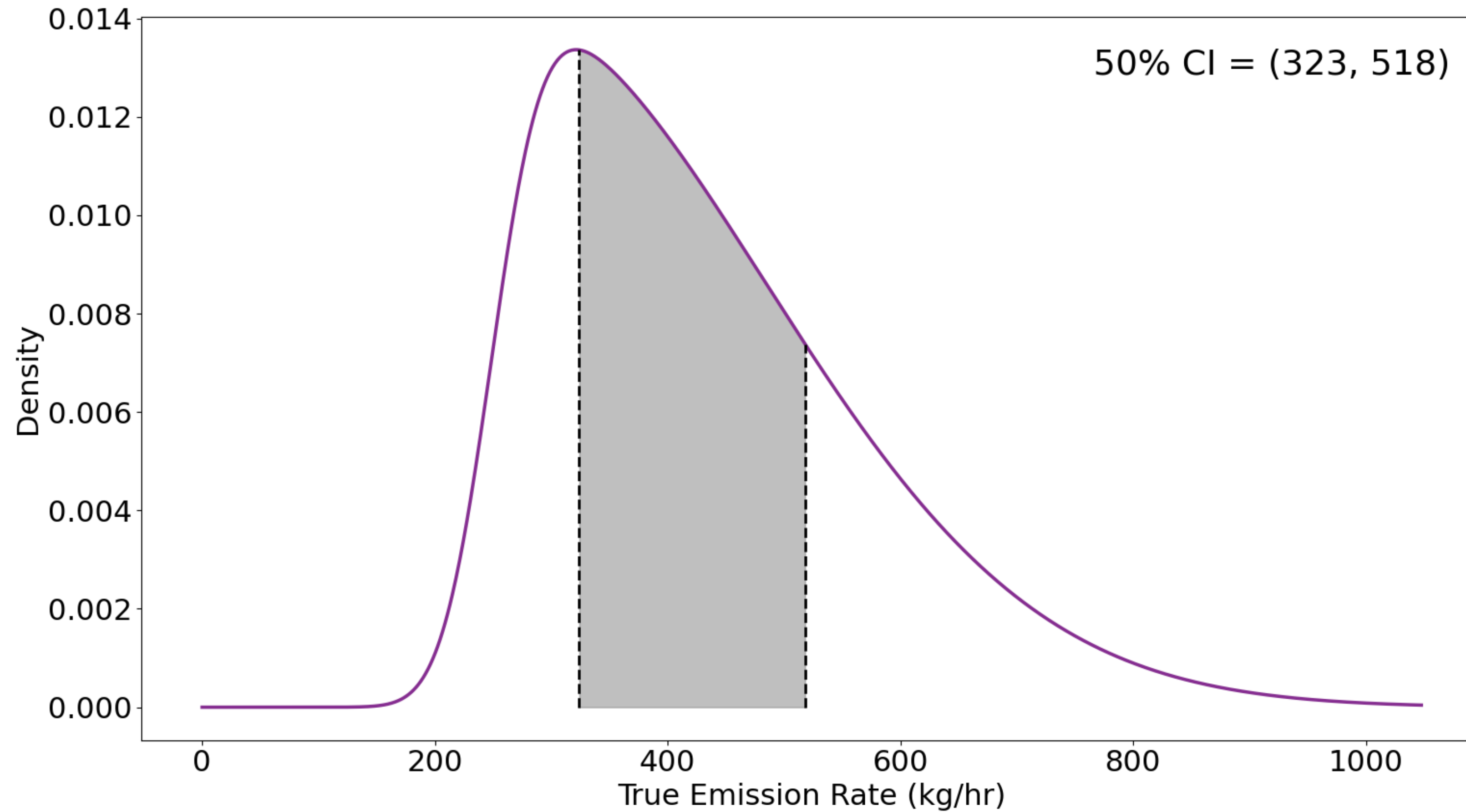
$$\text{Truth} = \text{Est.} \times \text{Est. Error} + \text{Est.}$$

Measured Emission Rate = 419 kg/hr



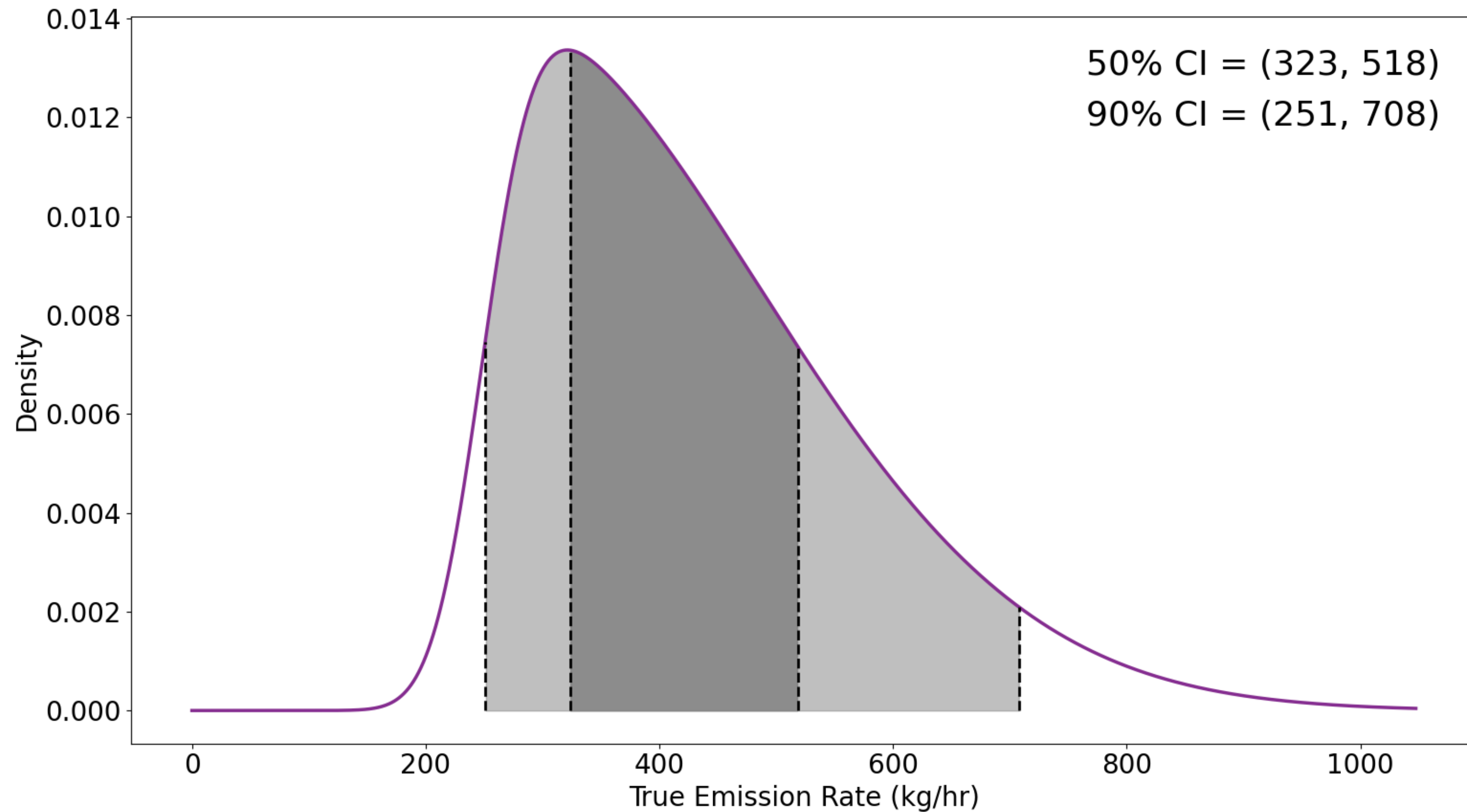
Use Example

Measured Emission Rate = 419 kg/hr



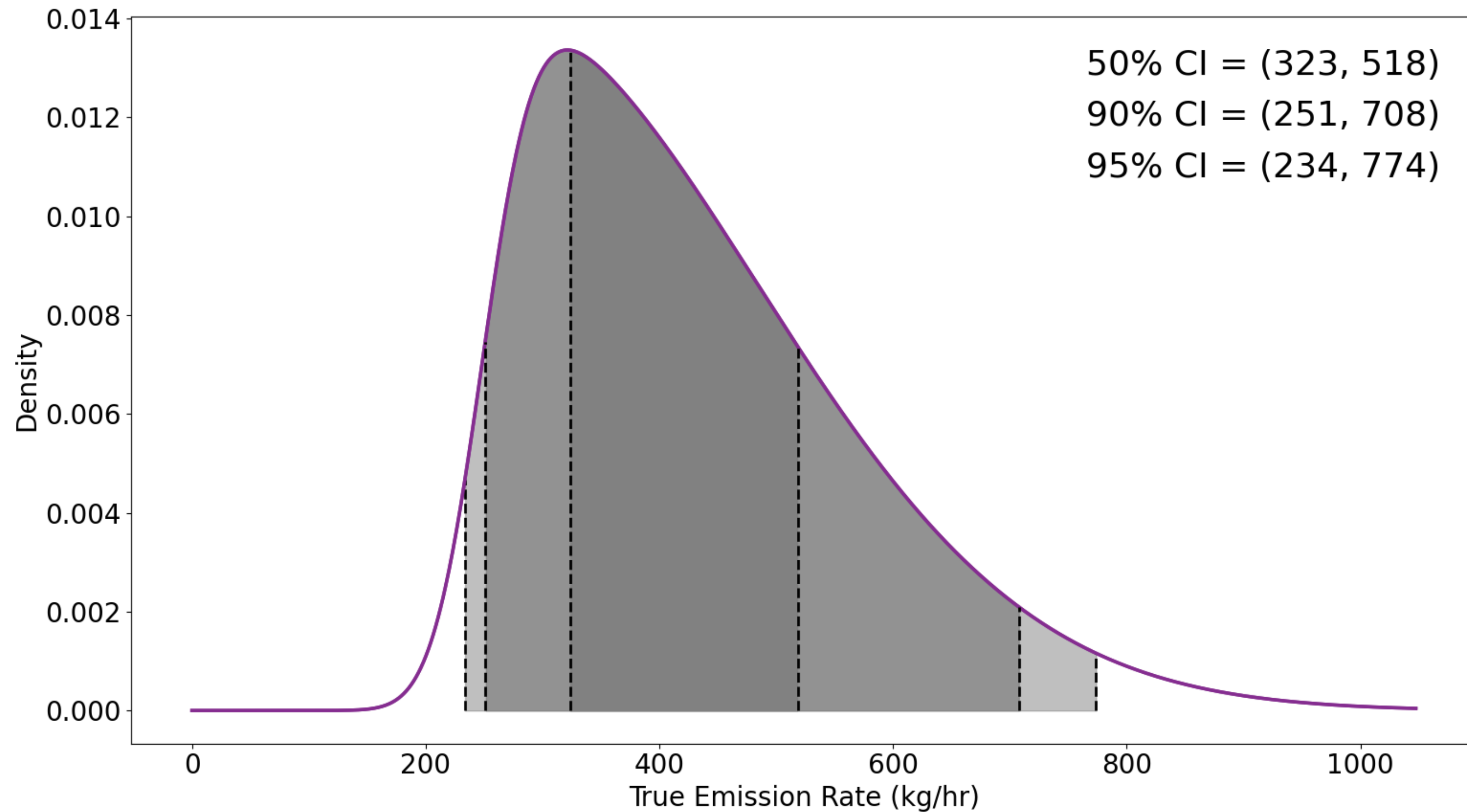
Use Example

Measured Emission Rate = 419 kg/hr



Use Example

Measured Emission Rate = 419 kg/hr



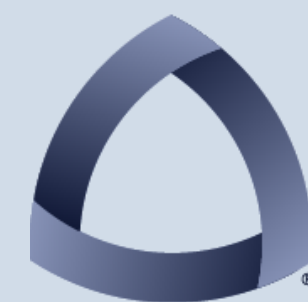
Implications

- Proposed framework generates a theoretical error distribution for any measured emission rate
 - ▶ Generates confidence intervals for individual measurements
 - ▶ Could help to construct error bounds for entire inventories
- Easily modifiable to use other predictors or multiple at once



Questions?

Thank you for attending!



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