

Development of a New Emission Inventory for Mobile Sources in Large Metropolitan Regions: Application of Traffic Emission Prediction Scheme (TEPs) in Quebec and Ontario

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Introduction

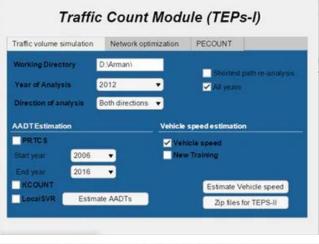
• With a changing urban mobility landscape (travel patterns and new vehicle types), it is critical to develop techniques for the generation of mobile source emission inventories at urban and regional scale.

Traffic Emission Prediction scheme (TEPs)

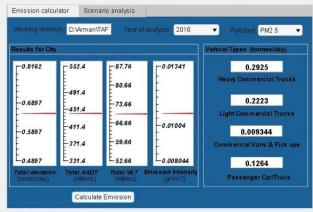
 TEPs improves the regional prediction of mobile source emissions through a combination of advanced spatiotemporal models and satelliteimage processing. TEPs merges shortterm on-road and satellite-based vehicle counts (extracted based on a combination of Convolutional Neural Networks and image processing techniques) with traffic count data at stations with long record lengths to predict traffic on roads with no traffic observations.



Traffic Emissions Prediction scheme

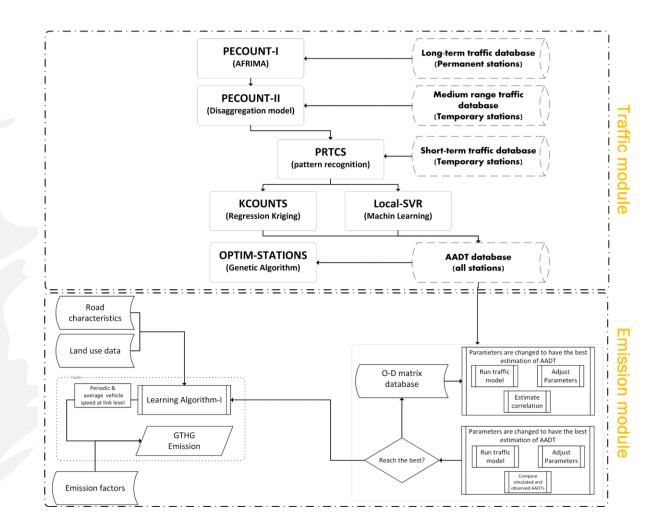


GHG module (TEPS-II)

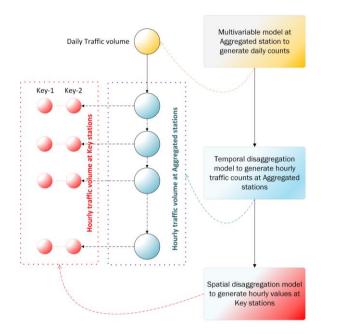


Theoretical basis

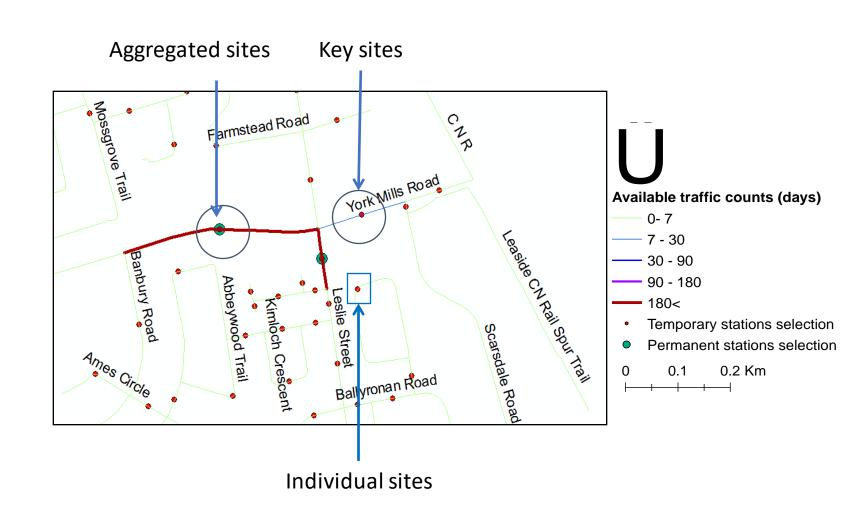
 The merging techniques include spatiotemporal disaggregation, pattern recognition, and trend analysis, which connect long and short-term counts. Subsequently, Annual Average Daily Traffic (AADT) is estimated for several years based on a combination of Supportive Vector Regression and Regression Kriging/Neural Network techniques for all roads across a network



PECOUNT-I & PECOUNT-II



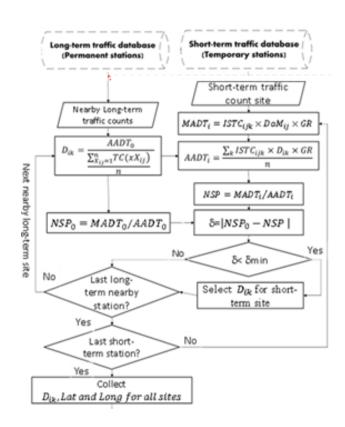
Spatio-temporal disaggregation model

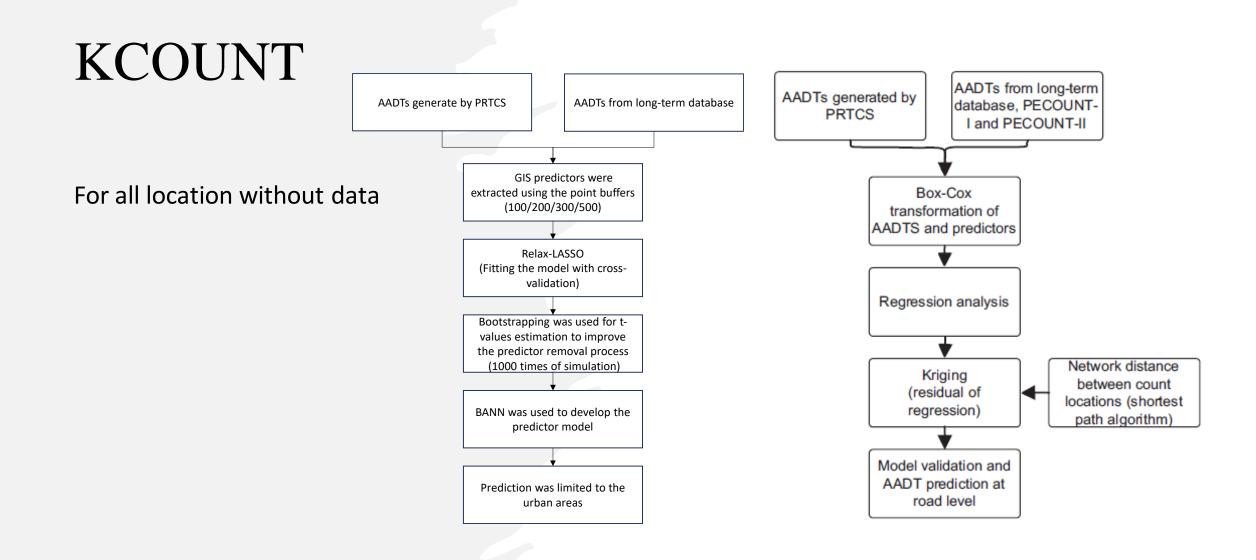


PRTCS

AADT prediction using Pattern Recognition Traffic Counts model

• Traffic Emission Prediction scheme (TEPs) uses a long record of traffic counts to extend downstream daily traffic counts; a pattern recognition approach further identifies a coefficient to estimate AADT from daily values. This technique provides a unique basis to use short-term traffic counts (e.g., one day) for longterm average traffic prediction (AADT).





Satellite data- a new data source

Expanding the database of short-term counts using aerial imagery

Vehicle detection from aerial images

Convolutional neural network (CNN

Road detection and extraction of road characteristics

•Image processing method

Time stamp of aerial images

•Based on shadows and sun position

Prediction of AADT from short-term image-based counts

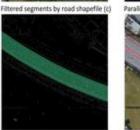
•Neural Network and road characteristics



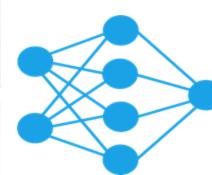


Level-line field and line segment (b





Vehicles detection



Daily traffic prediction

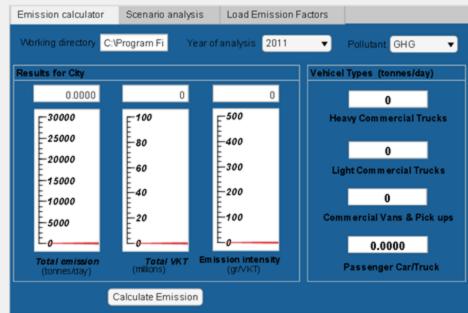
Road characteristic detection

8

EMISSION PREDICTION

Segment-level vehicle kilometers traveled (VKT) were multiplied by the corresponding emission factors to obtain segment emissions. The emission factor database was derived from the Mobile Vehicle Emissions Simulator (MOVES) platform developed by the United States Environmental Protection Agency.

GHG module (TEPS-II)



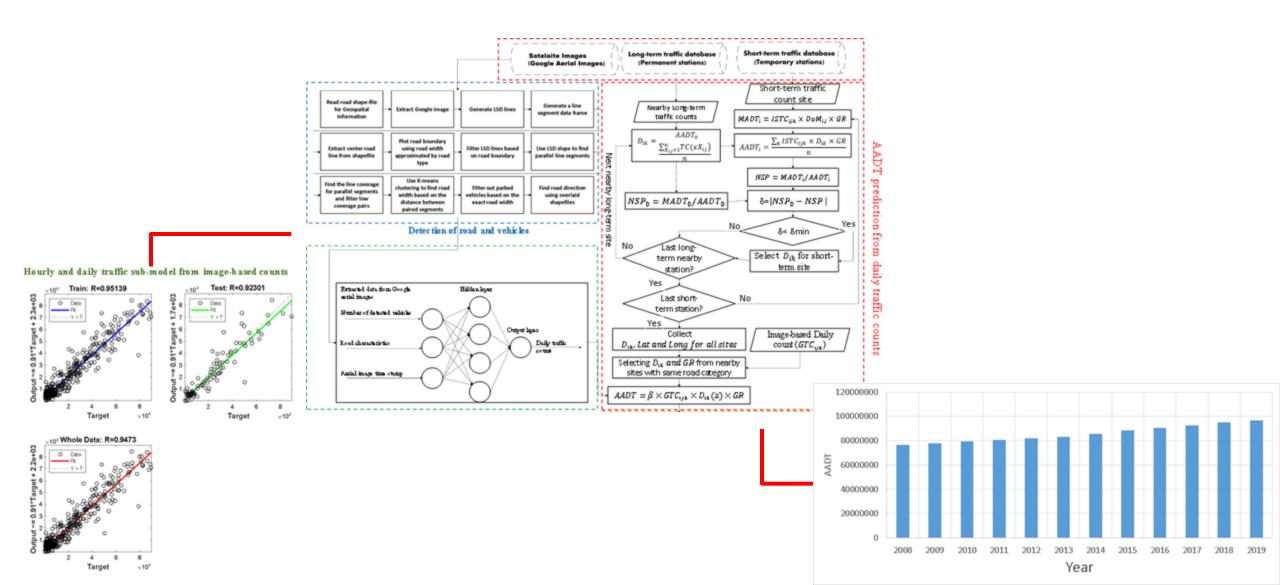
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Example for AADT and emission prediction at provincial scale

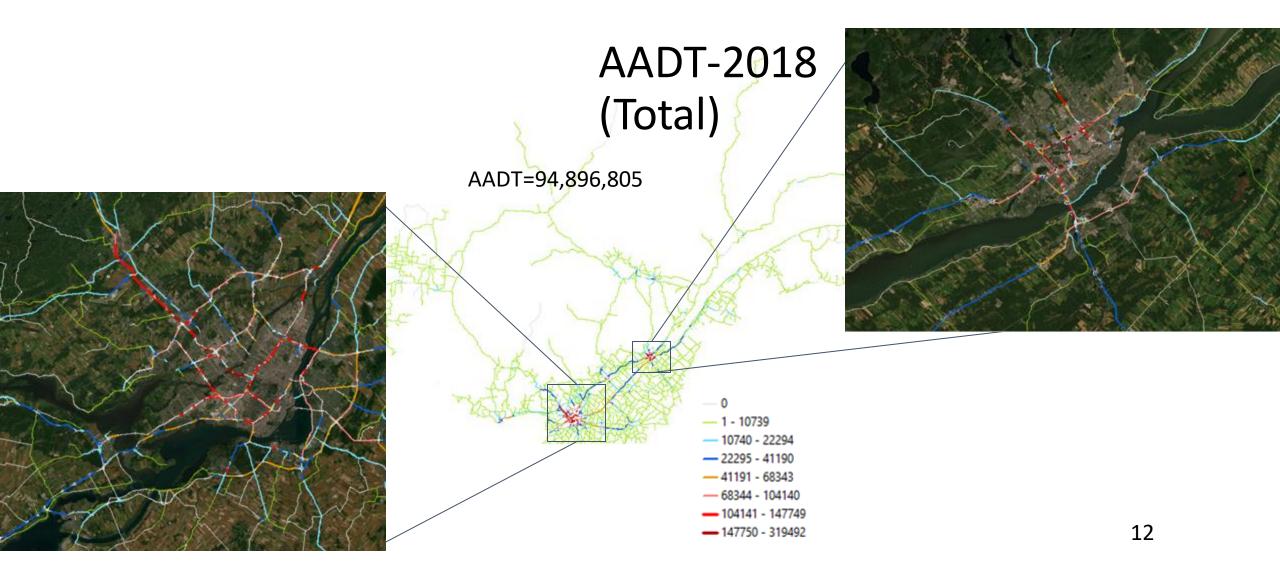
TEPs performance was evaluated in Quebec province and several Canadian metropolitan regions, including Toronto, Montreal, and Quebec. Multiyear road emission inventories for various pollutants were generated for all types of roads, including local and major roads and highways



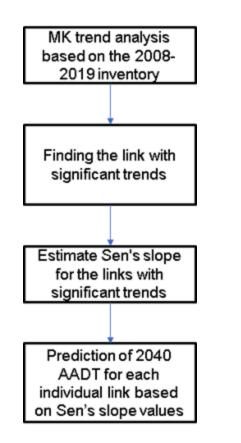
AADT inventory for provincial roads



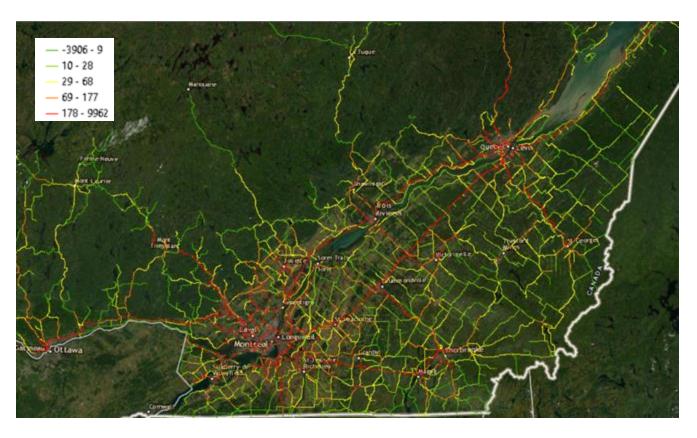
AADT inventory for provincial roads



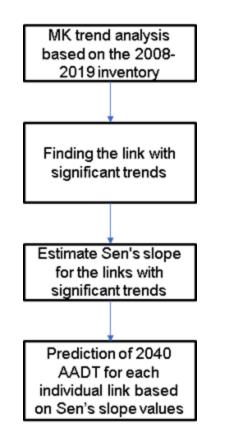
AADT inventory for provincial roads (2040 projection)



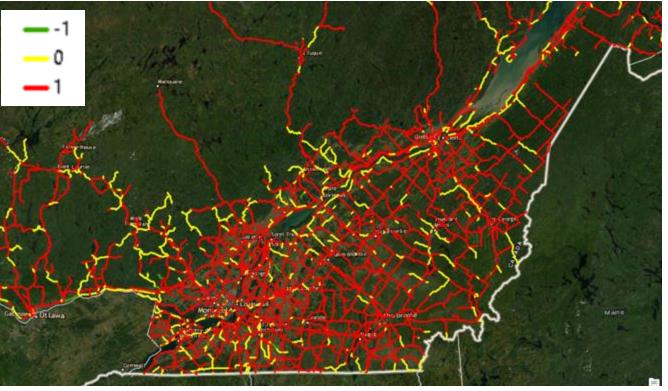
Sen's slope (Veh/year)-West/Southbound direction



AADT inventory for provincial roads (2040 projection)



Links with statistically significant (1 and -1 for positive and negative slopes) and insignificant trends (0)



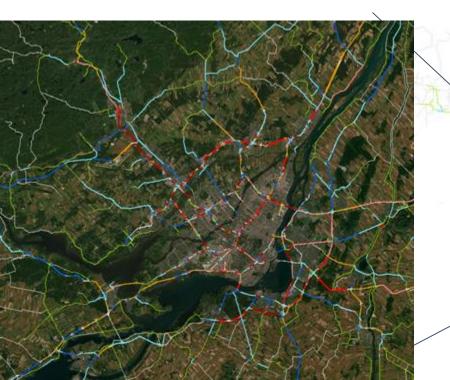
West/Southbound direction

AADT inventory for provincial roads (2040 projection)



AADT-2040 (Total)

AADT=134,353,654



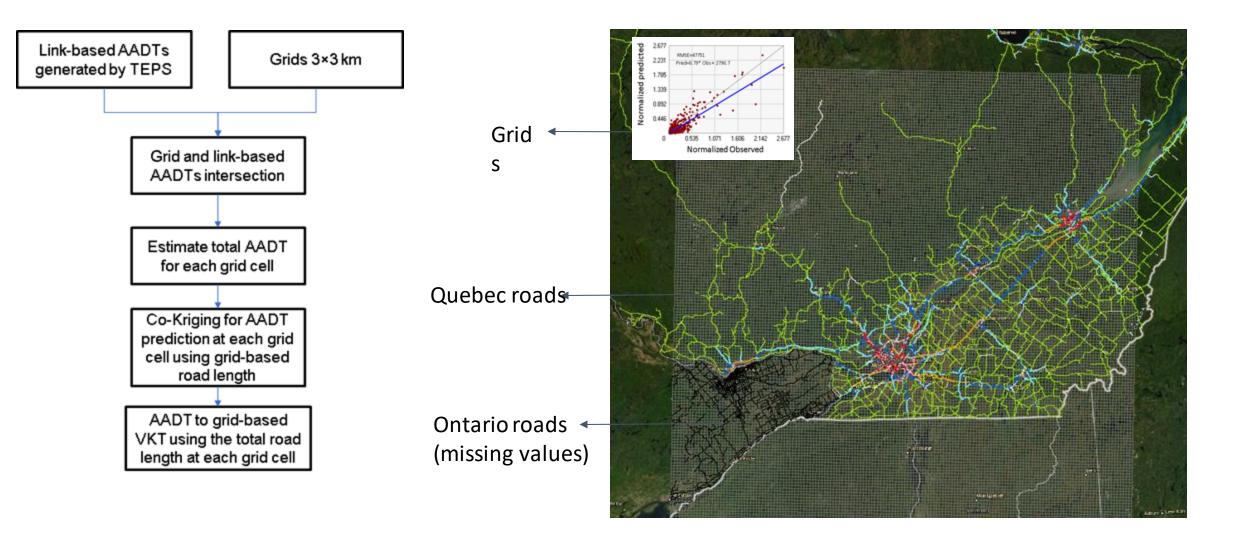
- 0 - 1 - 10739 - 10740 - 22294 - 22295 - 41190 - 41191 - 68343 - 68344 - 104140 - 104141 - 147749 - 147750 - 319492

Grid-based AADT over the entire modelling domain

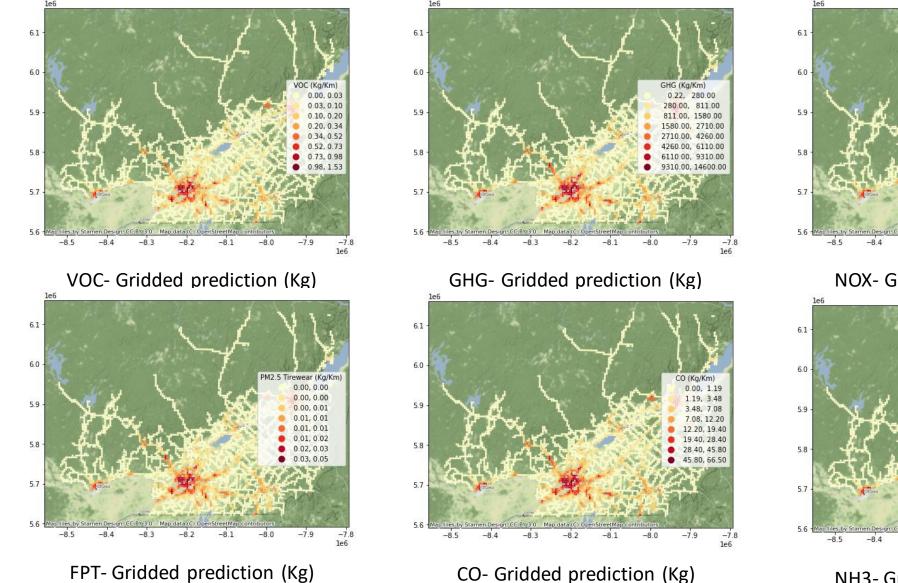




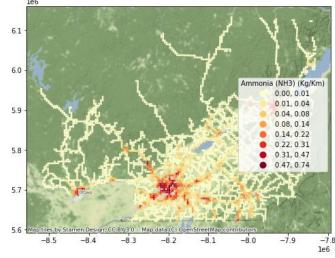
Grid-based AADT over the entire modelling domain



Grid-based 2018-AADT over the entire modelling domain



NOX- Gridded prediction (Kg)



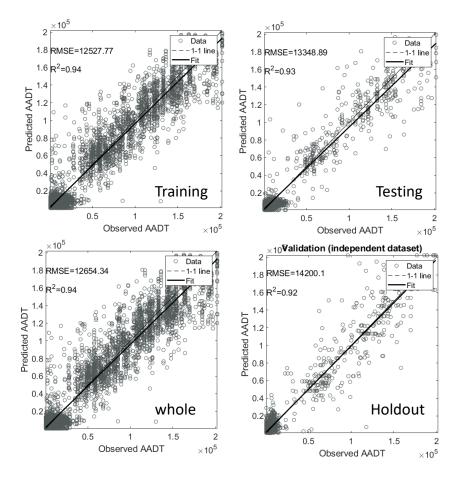
NH3- Gridded prediction (Kg)

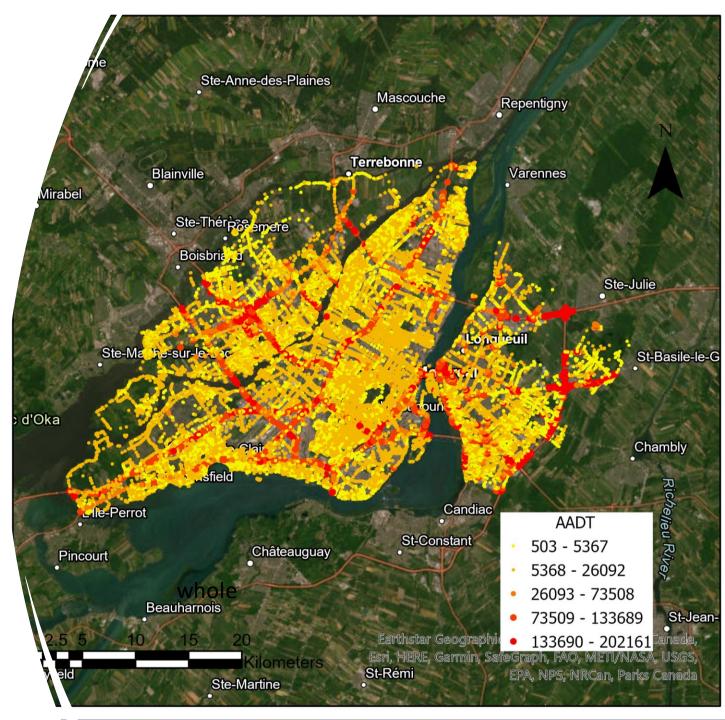
Traffic in the metropolitan areas and scenario analysis





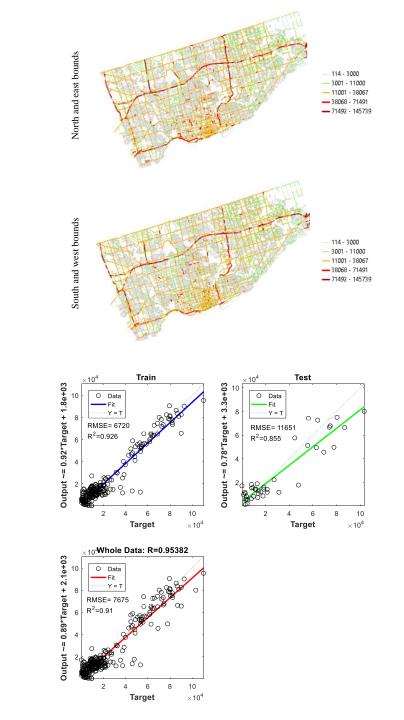
Example for AADT and emission prediction at urban scale



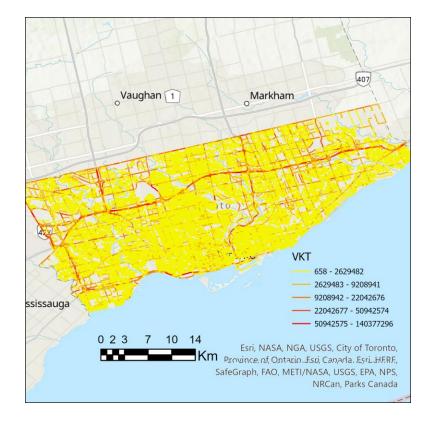


Example for AADT and emission prediction at urban scale- Toronto (Including Satellite images)

> Bayesian Regularization Artificial Neural Network (BR-ANN) for daily counts prediction from Satellite images

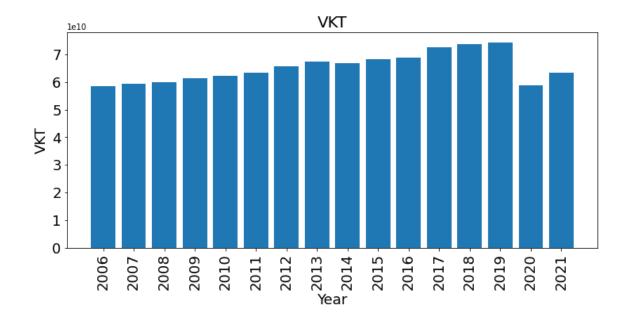


VKT (multiyear inventory) Prediction for Covid



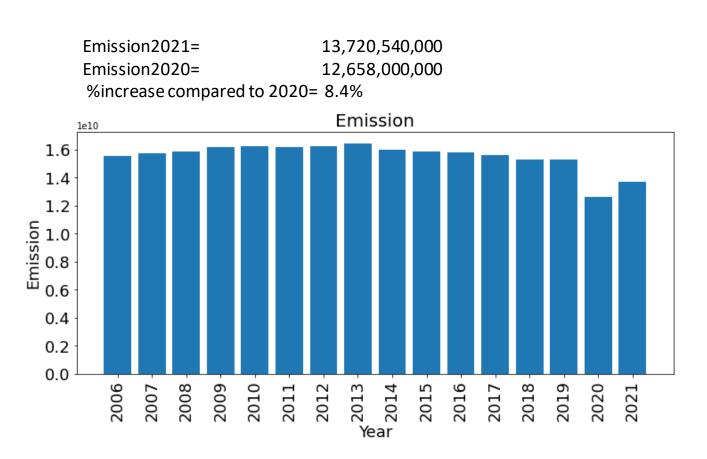
- VKT2021=
- VKT2020=

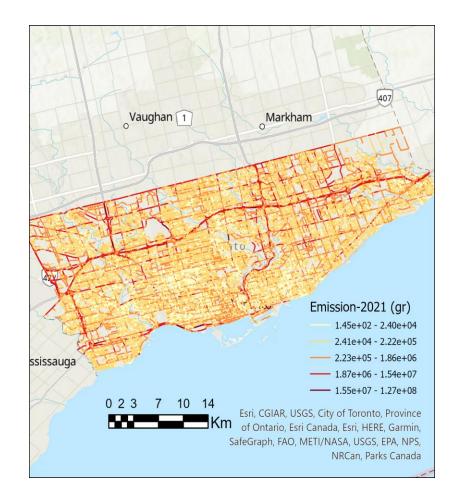
- 63,414,342,332
- 58,660,000,000
- %increase compared to 2020= 8.1% ۲



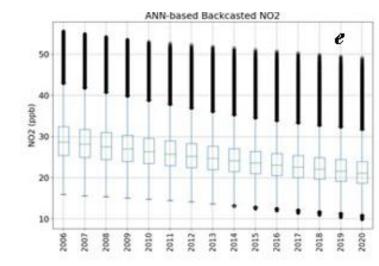
GHG emission

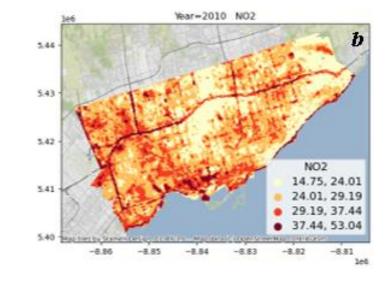
(multiyear inventory) Prediction for Covid

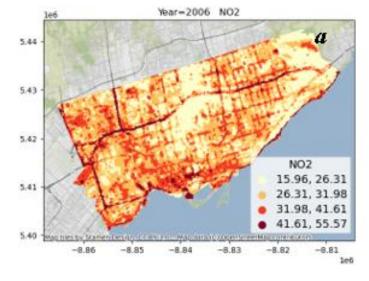




Backcasting the air pollution (NO₂ concentration)







Conclusion

- We developed a model (TEPs) of AADT, emission and air quality prediction based on vehicle counts, satellite-based road characteristics and vehicle detection.
- TEPs was developed to mine traffic count data in order to predict the emission across urban/provincial road network and over time.
- Since the proposed methodology works based on the observed traffic counts and images, using relationships that are extracted directly from the data, it is therefore transferable to other cities.
- As a benefit of using TEPs, it is possible to predict and backcast AADT, emissions and air pollution for any specific year.
- This scheme has the potential to truly shape the way urban transportation emission inventories are currently developed, providing robust vehicle activity data (through traffic counts) and the capability of tracking progress through time.